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# International Journal of Physical Sciences

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# **Seven-dimensional space-time and its objects: Arbitrary spin state, electromagnetic fields, mirror symmetry and superconductivity**

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**To form the basis spin states of a field, vector states of the multicomponent wave function to the four coordinates of Minkowski space that determine the position of the local observer have been added by angular extra dimensions that determine the orientation of the local observer. The generators of the Poincare group in the angular representation have been obtained. The Dirac equation (generalized for any spin) and Maxwell's equation have been designed from these generators. In the framework of transformations of the Lorentz group in angular representation united with its transpose representation, the transformations of the (generalized) Dirac equations that is similar to the Heaviside-Larmor transformations for Maxwell's equations have been performed. As a result, the Dirac equation for the Dirac monopole, which corresponds to a particle with mirror symmetry have been obtained. Indication of a low probability of the existence of the Dirac monopole had been obtained.**

**Key words:** Spinor representation of the Poincare group, seven dimensions of space-time, mirror symmetry.

## **INTRODUCTION**

Hidden harmony is stronger than the explicit one. Heraclitus Space-time and matter are inseparable from each other. Classical mechanics knows two classes of systems: "material points" and "rigid bodies". In building up a general mathematical theory applying to any system, one usually starts from the equations of motion of a material point. From a physical point of view, however, the idea of "rigid body" is as fundamental a conception as the idea of "material point" (Casimir, 1931). Quantum-mechanical theory of angular momentum of a rigid body has a strong position in the mathematical formalism of modern quantum physics (Bidenhander and

Lauk, 1984; Varshalovich, 1975). This formalism includes the use of Wigner D functions dependent on Euler angles  $\varphi, \theta, \gamma$  determining the orientation of the local observer in relation to the ordinary meter. This formalism allows to determine the direction of a vector in space, the orientation of the local observer, addition of vectors, basis states with spin and their transformation properties under rotation through the functions of  $\varphi, \theta$  and  $\gamma$  at once for all points in space without reference to a specific point  $x_1, x_2, x_3, t$ , but connected with the orientation of the meter.

In the space of orientations of the observer (of the rigid body) there exist Wigner  $D^j$  functions, for a half-integer

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value of  $j$  which are transformed with using the group  $SU(2)$  instead of  $SO(3)$  when turn in the space of  $x_1, x_2, x_3$  and  $t$  takes place. In Minkowski space there do not exist objects whose *functions are transformed using the group  $SU(2)$*  (Sventkovsky, 2004).

Similar to the fact that the position of the particle is described by wave function depending on the  $x_1, x_2, x_3$ , and  $t$ , the orientation of the particle (an electron is a point particle) also may be described by a wave function depending on its possible orientations  $\varphi, \theta$  and  $\gamma$ .

In this paper, the emphasis has been shifted from the consideration of transformations themselves to the objects of transformations. For this purpose, besides the ordinary coordinate system called the meter two local observers (ordinary and rotated) have been introduced in Minkowski space-time which have the center at the same point  $x_1, x_2$  and  $x_3$  related to the position of the particle field. The ordinary observers are parallel to the meter. The use of the ordinary local observer is due to the known position that a rotation of the meter in the neighborhood of  $x_1, x_2$  and  $x_3$  can be divided into two transformations: The translation of a point which does not change the angle variables and the rotation of the ordinary local observer around the point  $x_1, x_2$  and  $x_3$  in the coordinate system with center at the point  $x_1, x_2$  and  $x_3$  and by the same angle.

The transformation properties of the spin state under rotation of the meter are offered to describe identically under rotation of the rotated local observer.

Interpretation of the well-known principle of superposition (spin) states for multicomponent wave functions as the principle of superposition of states for any fixed direction at every point was the basis for the introduction of new angular dimensions for the wave function.

A multicomponent wave function describing vector fields, particles with spin in Minkowski space, is proposed equivalently interpreted as the presence of an internal rotational degree of freedom (field) at each local point that are not related to the spatial variables. Angular extra dimensions  $\varphi, \theta$  and  $\gamma$  have been introduced in Sventkovsky (2004), but a number of important provisions of the theory are not expressed or are expressed only partly. In Portnov (2011), there is a discussion of the use of these variables in the development of general relativity theory, but not at the quantum level.

The physical foundations for the introduction of extra dimensions for explaining the nature of multicomponent wave function with known Lorentz transformation properties of states with spin, intrinsic parity as an internal degrees of freedom of the fields are discussed in the article.

Symmetry of the equations of quantum mechanics and Maxwell equations has a higher order than the symmetry associated only with the group of Lorentz. A generalized Lorentz group corresponding to the unification of the

Lorentz group in the matrix (spinor, vector) representation and its transpose representation has been obtained in Sventkovsky (2004) for any  $j$  in operator form. The group of internal symmetry is considered as a sub-group of the generalized Lorentz group and corresponds to the transition from one type of particles, fields and representations to another.

The equivalence between the Schrodinger operator equation and Heisenberg's matrix mechanics was proved in 1927 for operators dependent on the time-space coordinates (Teschl, 2009). A similar construction (substitution of matrices by operators) concerned only with the operators acting on the angular variables which are introduced to explain the nature of spinors and vector fields is considered in the present paper. The relationship between Dirac matrices, the equations of Maxwell and generators of the generalized Lorentz group is also studied in the article.

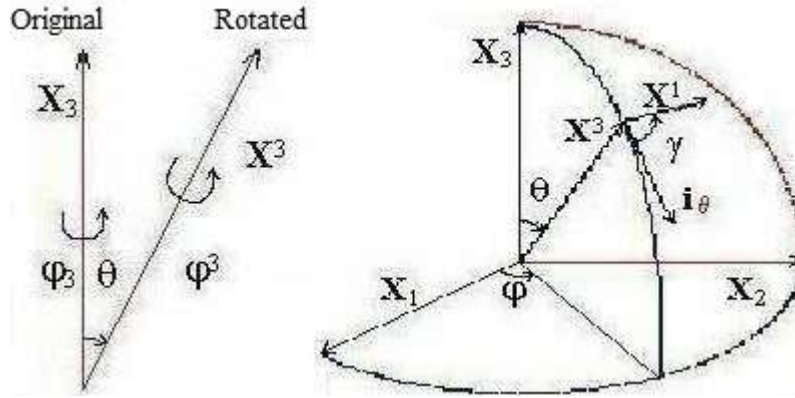
## TWO INTERNAL LOCAL OBSERVERS WITH THE CENTER AT ONE POINT

The meter is the original right Cartesian coordinate system. At the center of the point  $x_1, x_2$  and  $x_3$  original local observer with unit vectors  $\mathbf{X}_1, \mathbf{X}_2$  and  $\mathbf{X}_3$  parallel to the meter were introduced. For describing objects with zero size at the center of the point  $x_1, x_2$  and  $x_3$  a rotated local observer with unit vectors  $\mathbf{X}^{(1)}, \mathbf{X}^{(2)}$  and  $\mathbf{X}^{(3)}$  and with the orientation defined by three independent Euler angles  $\varphi, \theta, \gamma$  with respect to the local original observer were introduced as shown in Figure 1. In fact, instead of one rotated observer are introduced a lot of rotated observers  $\varphi, \theta$  and  $\gamma$ . Turning one rotated observer means turning a lot of the multidirectional rotated observers.

The superscript and the subscript in operators  $X^{(k)}, J^{(k)}, J_i, Q^{(k)}$  refer to respectively the rotated observer with unit vector  $\mathbf{X}^{(k)}$  and to the ordinary observer with unit vector  $\mathbf{X}_i$ . The rotation matrix can be written in a symmetrical form with respect to the two local observers (Bidenhander and Lauk, 1984):

$$\begin{aligned} R_{ij} &= (X^{(i)}, X_j), (\mathbf{X}^{(1)}, \mathbf{X}^{(2)}, \mathbf{X}^{(3)}) = R(\mathbf{X}_1, \mathbf{X}_2, \mathbf{X}_3) = R_3(\varphi) R_2(\theta) R_3(\gamma). \\ X^{(1)}_1 &= -\sin(\theta) \sin(\gamma) + \cos(\theta) \cos(\varphi) \cos(\gamma), X^{(2)}_3 = \sin(\theta) \sin(\gamma), \\ X^{(1)}_3 &= -\sin(\theta) \cos(\gamma), X^{(1)}_2 = \cos(\varphi) \sin(\gamma) + \cos(\theta) \sin(\varphi) \cos(\gamma), \\ X^{(2)}_1 &= -\sin(\varphi) \cos(\gamma) - \cos(\theta) \cos(\varphi) \sin(\gamma), \\ X^{(2)}_2 &= \cos(\varphi) \cos(\gamma) - \cos(\theta) \sin(\varphi) \sin(\gamma), \\ X^{(3)}_1 &= \sin(\theta) \cos(\varphi), X^{(3)}_2 = \sin(\theta) \sin(\varphi), X^{(3)}_3 = \cos(\theta), \end{aligned}$$

The generators of the rotation group  $J_k$  or angular momentum operators of rigid body will be called the generators of the vector rotations relative to the original local observer. The projections  $J_k$  onto the axis of the rotated local observer:  $J^{(k)} = (\mathbf{X}^{(k)} \mathbf{J})$  are considered in literature as the operators of the angular momentum of a symmetric top. Let  $\epsilon_{i,j,k}$  is the antisymmetric tensor  $\epsilon_{1,2,3} = 1$ .



**Figure 1.** The orientation of the rotated local observer with respect to the original local observer.

$$\begin{aligned}
 J_1 &= i \cos(\varphi) \operatorname{ctg}(\theta) \partial/\partial\varphi + i \sin(\varphi) \partial/\partial\theta - i \cos(\varphi)/\sin(\theta) \partial/\partial\gamma, \\
 J_2 &= i \sin(\varphi) \operatorname{ctg}(\theta) \partial/\partial\varphi - i \cos(\varphi) \partial/\partial\theta - i \sin(\varphi)/\sin(\theta) \partial/\partial\gamma, \\
 J^{(1)} &= -i \cos(\gamma) \operatorname{ctg}(\theta) \partial/\partial\gamma - i \sin(\gamma) \partial/\partial\theta + i \cos(\gamma)/\sin(\theta) \partial/\partial\varphi, \\
 J^{(2)} &= i \sin(\gamma) \operatorname{ctg}(\theta) \partial/\partial\gamma - i \cos(\gamma) \partial/\partial\theta - i \sin(\gamma)/\sin(\theta) \partial/\partial\varphi, \\
 J_3 &= -i \partial/\partial\varphi, \\
 J^{(3)} &= -i \partial/\partial\gamma, \\
 [J_i, J_n] &= i \varepsilon_{ink} J_k, [J^{(i)}, J^{(n)}] = -i \varepsilon_{ink} J^{(k)}, [J_i, J^{(n)}] = 0
 \end{aligned} \tag{1}$$

The operators  $J^{(n)}$  are generators of the transposed rotation group, they are also generators of a group of rotations of the rotated local observer  $X^{(1)}, X^{(2)}, X^{(3)}$  relative to himself. It is impossible to interpret the rotation by means of operators  $J_k$  by the rotation by means of operators  $J^{(n)}$ , as the operator  $J_k$  cannot be obtained from  $J^{(n)}$  by using a unitary similarity transformation (Bidenhander and Lauk, 1984). The operators  $J_k = X^{(n)}_k J^{(n)}$  are projections of  $J^{(n)}$  onto the axis  $X_k$  and invariant under rotation using  $J^{(n)}$ .

Vectors in coordinate system  $X^{(k)}$  will be called isovectors and rotation using  $J^{(k)}$  will be called rotation in the isovectors space.

Wigner D functions,  $D^j_{mm'}$  are the eigenfunctions of the angular momentum operators  $J_3, J^{(3)}, J^2 = J_k J_k$ . This corresponds to the symmetry between the original observer and rotated observer and so it is written in this form:

$$\begin{aligned}
 D^{*(1/2)} &= (\xi^{(1/2)}, \xi^{(-1/2)}), \quad \xi^{(1/2)} = (\psi_1, \psi_2), \quad \xi^{(-1/2)} = (\psi_3, \psi_4). \\
 \psi_1 &= \cos(\theta/2) \exp(i\gamma/2 + i\varphi/2), \\
 \psi_3 &= -\sin(\theta/2) \exp(-i\gamma/2 + i\varphi/2)
 \end{aligned} \tag{2}$$

$$\psi_2 = \sin(\theta/2) \exp(i\gamma/2 - i\varphi/2), \quad \psi_4 = \cos(\theta/2) \exp(-i\gamma/2 - i\varphi/2)$$

The known symmetry operator between the original local observer and the rotated local observer has the form  $W$ :  $\varphi' = \gamma, \theta' = -\theta, \gamma' = \varphi$ , (Bidenhander and Lauk, 1984) and formally implements permutation by the places of these observers. The operator  $W$  corresponds to the operation

of transposition for the representation of a rotation group which is denoted by icon  $\bar{\cdot}$ . The icon  $\bar{\cdot}$  is the operation of complex conjugation. For example:

$$J^{(k)} = (-1)^{k+1} W J_k, \quad W D^j = D^{jT}, \quad X^{(k)}_n = (-1)^{k+n} W X^{(n)}_k. \tag{3}$$

The Euler angles  $\varphi, \theta$ , and  $\gamma$  that determine the orientation of the local rotated observer relatively to the meter were named as extra dimensions to the four coordinates of the Minkowski space.

The elements of the new space  $\varphi, \theta$  and  $\gamma$  are Wigner D functions,  $D^j_{m,m'}$  which are transformed using the group  $SU(2)$ . The double space of all possible orientations for the rotated observer corresponds to the space domain of the angles Wigner D functions with volume  $\int \int d\Omega d\gamma = 16 \pi^2$ ,  $d\Omega = \sin(\theta) d\theta d\varphi$ ,  $\Omega$  is a solid angle (Bidenhander and Lauk, 1984). The Wigner D functions,  $D^{(j)}, X^{(k)}_n$  are bases of orthogonal functions:

$$\langle \xi^{(m)}_i | \xi^{(k)}_n \rangle = \int \int \xi^{(m)*}_i \xi^{(k)}_n d\Omega d\gamma = \delta_{i,n} \delta_{m,k} / b^2$$

where  $b = \sqrt{(2j+1)/(4\pi)}$ ,  $\langle, \rangle$  icons are used only for the orientations space, and  $\delta_{i,k}$  is the Kronecker delta,  $\delta_{k,k} = 1$ .

Any column  $\xi^{(m)}$  of the matrix  $D^{(j)}$  is transformed in the same manner as a spinor  $j$  under spatial rotation and corresponds to a complete set of basis vectors describing states with spin  $j$ , (Varshalovich, 1975), as  $J \xi^{(m)T} = \xi^{(m)T} S$ ,  $[S_i, S_n] = i \varepsilon_{ink} S_k$ ,  $S_i$  is the matrix operator of angular momentum.

The rotated observer for state  $j$  also as original observer has  $2j+1$  degrees of freedom corresponding to the analog of the spin projections  $m' = -j, \dots, +j$ ,

$$J^{(3)} \xi^{(m)} = m' \xi^{(m)}$$

For example  $j=1/2, 2S_n = \sigma_n$  are Pauli matrices. Let  $\xi_m$  be any  $m$  string of the matrix  $D^j$ . Using the operator  $W$ , the identities were obtained:



$$J^{(k)}\xi_m = \xi_m S_k^T, S_k^T = (-1)^{k+1} S_k, \xi_m = W \xi^{(m)T},$$

$$J^{(+)} = J^{(1)} - iJ^{(2)}, J^{(+)}\xi^{(m)} = \sqrt{(j-m')(j+m'+1)} \xi^{(m+1)}$$

Taking into account the completeness of the system of bases  $D^j$ , any spinor  $j$ ,  $\psi^T = (\psi_j, \psi_{j-1}, \dots, \psi_{-j})$  can be represented as a linear combination  $\xi^{(m)}$  of the spinors  $j$ , which depend only on  $\varphi, \theta$  and  $\gamma$  (Bidenhander and Lauk, 1984).

The transformation using exponential operator is taken using the Baker-Campbell-Hausdorff formula:

$$\psi' = \exp(A) \psi, \exp(A) = 1 + A + A^2/2! + A^3/3! + \dots;$$

$$B' = \exp(A) B \exp(-A),$$

$$\exp(A) B \exp(-A) = B + [A, B] + 1/2! [A, [A, B]] + 1/3! [A, [A, [A, B]]] + \dots$$

The presence of well-known transformational properties of these bases of spinors  $\xi^{(m)}$ , vectors  $X^{(k)}$ , (Bidenhander and Lauk, 1984) is based on the premise that the bases themselves are presented as the rotation matrix  $D^j$ , (R) under the turn of the original local observer onto Euler angles  $\alpha, \beta$  and  $c$ .

$$D^j(\varphi', \theta', \gamma')^{*T} = D^j(\varphi, \theta, \gamma)^{*T} D^j(\alpha, \beta, c) =$$

$$= (\exp(-i\alpha J_3) \exp(-i\beta J_2) \exp(-i\gamma J_3)) D^j(\varphi, \theta, \gamma)^{*T}, \quad (4)$$

$$D^j(\alpha, \beta, c) = \exp(-i\alpha S_3) \exp(-i\beta S_2) \exp(-i\gamma S_3).$$

The rotations of the original local observer (Equation 4) and the rotated local observer onto angles  $\omega$  are also realized by the rotation operators  $\exp(-i\omega J_n)$  and  $\exp(-i\omega J^{(k)})$ .

We have identities:

$$\exp(-i\omega J_n) (X^{(p)1}, X^{(p)2}, X^{(p)3}) = (X^{(p)1}, X^{(p)2}, X^{(p)3}) R_n(\omega),$$

$$\exp(-i\omega J^{(k)}) (X^{(k)1}, X^{(k)2}, X^{(k)3}) = (X^{(k)1}, X^{(k)2}, X^{(k)3}) R_k(\omega)^T$$

$$\exp(-i\omega J_n) (\psi_1, \psi_2) = (\psi_1, \psi_2) \exp(-i\omega \sigma_n)_T$$

$$\exp(-i\omega J^{(k)}) (\psi_1, \psi_3) = (\psi_1, \psi_3) \exp(-i\omega \sigma_k)_T$$

The known spatial transformation and Lorentz transformation can be obtained in two equivalent ways, both with the help of generators of the Lorentz groups and with the help of the transformation of angles  $\varphi, \theta$  and  $\gamma$  which correspond to the transformations of the vectors  $X^{(1)}, X^{(2)}$  and  $X^{(3)}$ . For example, rotating the meter around the  $x_3$  axis by an angle  $\alpha$  is accompanied by a transformation of the angle  $\varphi' = \varphi - \alpha$ , hence  $\xi^{(\pm 1/2)'} = \exp(-i\alpha \sigma_n/2) \xi^{(\pm 1/2)}$  is gotten.

Assuming that the spinors  $\xi^{(\pm 1/2)}$  are a Weyl spinors which has the known Lorentz transformation with velocity,  $v = |v|/x_3$ ,  $\text{th}(\chi) = v/c$ ,  $\xi^{(\pm 1/2)'} = \exp(\pm \chi) \xi^{(\pm 1/2)}$  and taking into account the symmetry by angle  $\varphi$ , the following angular transformation were obtained:  $\varphi' = \varphi$ ,  $\gamma' = \gamma$ ,  $\text{tg}(\theta'/2) = \exp(-\chi) \text{tg}(\theta/2)$ ; and a scale transformation of the basis which is the same for each  $j$ ,  $D^j$ , in the class 2j. Further, that this transformation does not change the orthogonality between the vectors  $X^{(n)}$  can be verified. Substituting the Lorentz transformation of  $\psi_k$  into identity:

$$X^{(3)}_3 = \psi_1 \psi_4 + \psi_2 \psi_3, X^{(0)}_0 = \psi_1 \psi_4 - \psi_2 \psi_3, X^{(1)}_3 = \psi_3 \psi_4 - \psi_1 \psi_3,$$

$$X^{(2)}_3 = \psi_3 \psi_4 + \psi_1 \psi_3, X^{(n)}_k = \psi_2 J^{(n)} J_k \psi^*, \Psi = (\psi_1, \psi_2, \psi_3, \psi_4).$$

That the Lorentz transformation- $X^{(3)}_3, X^{(0)}_0$  and  $x_3, t$  is realized in the same way as a four-dimensional vector  $x, t$  and  $X^{(3)}, X^{(0)}$  has a length of zero was obtain. Also that  $X^{(1)}, -X^{(2)}$  are transformed as bivector  $E$  and  $H$  of the electromagnetic field  $X^{(1)}_3 = X^{(1)}_3, X^{(2)}_3 = X^{(2)}_3$  was obtained. For a unified description of states with spin  $j$ , vector and tensor fields dependent on the orientation of the meter, we introduce the state of a class 2j, as a class of functions  $\Psi = \psi C$  which may be represented by a homogeneous polynomial of degree 2j of  $\psi_k$ , (2) (Varshalovich, 1975). This class corresponds to the principle of superposition of states. For example, the Wigner D function,  $D^j$  has a class 2j. The Lorentz transformation does not change the class 2j of functions  $\Psi$  since  $\psi_k$ , (2),  $j=1/2$  are linearly transformed.

The introduction of the state of class 2j is also associated with the expansion of the description of spinors  $j$  under the Lorentz transformation and is also connected with the overcoming of the difficulties associated with the ambiguity of the transformations of the wave function from the angular variables and which is also of the analogous difficulties described in Cartan (1927) under the matrix interpretation.

Example, under the Lorentz transformation of spinor  $j$  or  $D^j$  may appear additional summands (components) in the form spinor  $j-1, j-2$  or  $X^{(0)}_0 D^{j-1}, X^{(0)}_0{}^2 D^{j-2}$ , where  $X^{(0)}_0 = \psi_1 \psi_4 - \psi_2 \psi_3 = 1$  is a dimensional unit function of class 2. These summands do not change the class and do not appear under the spatial rotations.

In addition, the following operators can be formally represented in the identical ladder form that does not change the class (Jante and Schroers, 2016):

$$8J_3 = \psi_1 \partial/\partial \psi_1 - \psi_2 \partial/\partial \psi_2 + \psi_3 \partial/\partial \psi_3 - \psi_4 \partial/\partial \psi_4,$$

$$4J = \psi_2 \partial/\partial \psi_1 + \psi_4 \partial/\partial \psi_3, 4J^{(+)} = \psi_1 \partial/\partial \psi_3 + \psi_2 \partial/\partial \psi_4$$

The states with spin 1/2 has the next unique property: In the summation of states  $\psi_1, \psi_2$  (or  $\psi_3, \psi_4$ ),  $C = (C_1, C_2)$ ,  $\Psi = C_1 \psi_1 + C_2 \psi_2$  that corresponded to different orientations of spin, there is always such a rotated coordinate system  $X'_k = C \sigma_k C^T$  in which the spin is described by  $C' = (1, 0)$  and  $\Psi$  has the same form  $\Psi = \psi_1$ . There are only two independent forms (functions)  $\psi_1$  and  $\psi_4$  except for their linear combination, where  $\psi_1 = \psi_4$ . This property will be named to the property unchangeability of form of the angular function when similar states are added.

A multicomponent wave function  $C = (C_j, C_{j-1}, \dots, C_{-j}) = C_k |k\rangle$  corresponding to the spin (vector) states in the isotropic Minkowski space is proposed equivalently (one to one) to describe as a one-component wave function  $\Psi = C_k \psi_k$  space, where  $|k\rangle = (0, \dots, 0, 1, 0, \dots, 0)$  is unit basis,  $C_k$  depends only on  $x_1, x_2, x_3, t$  and  $\psi_k$ , depends only on  $\varphi, \theta$  and  $\gamma$ . This corresponds to the replacement in the wave function of the matrix basis  $|k\rangle$  by an operator basis  $\psi_k$  with the same transformation properties as for

the matrix basis using group SU(2).  $\varphi$ ,  $\theta$  and  $\gamma$  may be interpreted as the possible orientation of the particle. The decomposition of  $\Psi$  in the basis  $\psi_k$  corresponds to the multicomponent wave function C.

$$C_i = \langle \Psi | \psi_k \rangle, J_3 \Psi_m = m \psi_m, C^T C = \langle \Psi | \Psi \rangle, \langle \psi_i | \psi_k \rangle = \delta_{ik}.$$

For the physical meter in Minkowski space angular dimensions are hidden, internal and not observable, that is, all physical quantities at each point of space are calculated as average values over double the space of all orientations.

The elements of the seven-dimensional space are the one-component wave functions  $\Psi = \psi C$ .

Spatial transformation properties of spinors C are provided by the choice of  $\psi$  in the form of the spinor as any a linear combination of spinors  $\xi^{(m)}$ , j and Sommerfeld conditions, according to which the wave function  $\Psi = \psi C$  must be invariant under the Lorentz transformations  $\psi C = \psi' C'$ . Therefore, the transformation properties of basis  $\psi$  and C are related to each other, namely:

$$\text{if } \psi'^T = U \psi^T, C' = V C \text{ then } U^T V = 1, V = (U^{-1})^T$$

The rotation matrices U and V are unitary matrices so  $V = U^*$ . For  $\Psi = \psi C$  the vectors  $\psi = X^{(k)}$  and C have the same (identical) transformational properties as:

$$U = R(\alpha, \beta, \gamma)^{-1}, V = R^{-1}$$

For the spinor we have:

$$\psi'^T = D^j(\alpha, \beta, \gamma)^T \psi^T, C' = D^j(\alpha, \beta, \gamma)^T C, (\psi_1', \psi_2') = (\psi_1, \psi_2) \exp(-i\omega \sigma_n), C' = \exp(i \omega \sigma_n) C,$$

Lorentz transformation properties of spinor C are provided selecting  $\psi$  in the form specific of a linear combination of  $\xi^{(m)}$ , j which satisfy the famous Lorentz transformations of the spinor C.

All dimensions  $x_1, x_2, x_3, t$  and  $\varphi, \theta,$  and  $\gamma$  are mutually independent, but their transformational properties, except translation, are interconnected. The transformation properties of fields (vector, spin, etc.), except translation, are fully described the transformation properties of the basis functions of  $\varphi, \theta$  and  $\gamma$ .

Note that a field is present only in C, but  $\psi$  has no field, because  $\varphi, \theta,$  and  $\gamma$  have no relation to the coordinates  $x_1, x_2$  and  $x_3$  and to the position of the local meter. The initial values  $\varphi, \theta$  and  $\gamma$  (countdown) are related only to the orientation of the meter. Generators of the group  $J^{(k)}$ ,  $J_n, \partial/\partial\varphi, \partial/\partial\theta$  and  $\partial/\partial\gamma$  act only on basis functions  $\psi$  in  $\Psi = \psi C$ , but not on the field C.

Each representation of spinors  $\xi^{(k)}$ ,  $k=-j, j,$  may have its own invariant  $\Psi_k = C^{(k)} \xi^{(k)}$  under spatial rotations. After completing the Lorentz transformation (Sventkovsky, 2004) for arbitrary spinor  $\xi^{(k)}$  which is a basis of spatial

rotations, the full extended Lorentz basis j was gotten. Moreover, the extended components of the basis are also spinors corresponding  $j'=j-1, j-2, \dots, X^{(0)}_0 \xi^{(n)}, X^{(0)}_0{}^2 \xi^{(n)}$ .

The wave function  $\Psi$  of the class  $2j$  can be composed of  $2j+1$  independent Lorentz invariants  $\Psi^{(j)}_k = C^{(k)} \xi^{(k)} + C^{(n)} \xi^{(n)}$  obtained from  $2j+1$  invariants of  $C^{(k)} \xi^{(k)}$ ,  $k=j, j-1, \dots, -j$  under spatial rotations, plus the invariant  $C^{(n)} \xi^{(n)}$  obtained via extended Lorentz basis  $\xi^{(k)}$ .

**Theorem 1**

A spatial inversion leads to internal inversion  $\hat{I}$ .  $\hat{P}$ :  $t'=t, x'_i = -x_i; \hat{I}: \varphi' = \pi + \varphi, \theta' = \pi - \theta, \gamma' = \pi - \gamma$ , which is a equivalent to the turn of the rotated local observer about axis  $X^{(2)}$  by angle  $\pi$ . This follows from the identities:

$$\hat{I} \xi^{(\pm j)} = (-1)^{j \mp j} \xi^{(\mp)}, \hat{I}^2 \xi^{(\pm j)} = (-1)^{2j} \xi^{(\pm j)}, J_i = \hat{I} J_i, \hat{I} X^{(k)} = (-1)^k X^{(k)}, \hat{I} = \exp(i\pi J^{(2)})$$

The law of conservation of parity is directly related to the conservation of symmetry between the left and the right. The bases  $D^j_{m,m'}$  and  $D^j_{m,-m'}$  are linked by inversion transformation  $\hat{I} D^j_{m,m'} = (-1)^{j-m} D^j_{m,-m'}$ .

This allows to divide the entire basis into two equal groups of basis, except the case  $m'=0$  for the whole j. The group of bases  $m' > 0$  is called the left and its mirror  $m' < 0$  is called the right. The difference (balance) between the left and the right, with weight  $m'$ , is calculated as the average value of the operator  $J^{(3)}$ . For example:

$$\Psi = C^{(m')} D^j_{m,m'} + C^{(-m')} D^j_{m,-m'}, \langle \Psi | J^{(3)} | \Psi \rangle = b^2 = m' (|C^{(m')}|^2 - |C^{(-m')}|^2)$$

The complex conjugation operator has the form:

$$\exp(i\pi J^{(2)}) \exp(-i\pi J_2) D^j_{m,m'} = D^j_{m,m'}^*$$

**The models of the electromagnetic field**

In accordance with the quantum formalism, to describe the electromagnetic field, besides **E, H** we introduce the wave function in the form:

$$\Psi_{EH} = \mathbf{E} X^{(1)} + \mathbf{H} X^{(2)}, \Psi_A = \mathbf{A} X^{(3)} + A_0 C, X^{(0)}_0, \mathbf{F}^{(1)} = \mathbf{E}, \mathbf{F}^{(2)} = \mathbf{H}, \mathbf{F}^{(3)} = \mathbf{A}, F^{(0)}_0 = A^0 C, \mathbf{F}^{(k)} = b^2 \langle \Psi | \mathbf{X}^{(k)} \rangle, \mathbf{F}^{(\pm)} = \mathbf{F}^{(1)} \mp i \mathbf{F}^{(2)}$$

**E, H and A, A<sub>0</sub>** may be considered as the amplitudes of the wave function of basic states of the electromagnetic field. The bases of the vector electromagnetic field directed along the axes of  $x_k$  in the symmetric form  $X^{(n)}_k, X^{(0)}_0$  with respect to two observers  $X^{(3)}, X_3$  have been found from the well-known transformation properties of the electromagnetic field and from the condition of invariance  $\Psi = \psi C$ .

The bases  $X_k^{(n)}$ ,  $X_0^{(0)}$  correspond to a complete set of orthogonal basis functions for the state of the class  $2j=2$ . The wave function, the electric field and the magnetic field has the form.

Why is the sum of two electrical vectors equal to the electric vector?

Because basis functions  $X_k^{(p)}$ , under their arbitrary addition at  $p$  constantly have property unchangeability, same functional dependence on angular dimensions (analog of property of form) in some rotated coordinate system, which always exists. Namely: for any vector states  $C=(C_1, C_2, C_3)$ ,  $\Psi=CX^{(p)}$ , there is always such a rotated coordinate system  $X_3'=C'/|C'|$  in which vector  $C'=(0, 0, |C|)$  and  $\Psi'=C'_3X_3^{(p)}$ . That is,  $\Psi'$  have the same functional dependence with  $X_3^{(p)}$ . Example:

$$X_2^{(p)}=\exp(i\pi/2J_1) X_3^{(p)}, X_1^{(p)}=\exp(-i\pi/2J_2) X_3^{(p)}, \\ X_2^{(p)}=X_1^{(p)}(\varphi+\pi/2).$$

According to the principle of superposition of states, the addition of vectors of the electric field and of the magnetic field coincides with the addition of their models  $\Psi$  as a function of the angles  $\varphi$ ,  $\theta$  and  $\gamma$ . For example:

$$\Psi=EX^{(1)}, \Psi=HX^{(2)}, \Psi(E_1)+\Psi(E_2)=\Psi(E_1+E_2).$$

For the class 2, only vector basis, but not spin basis has this property of the same form. There are only three independent the forms for  $j=1$ , except for their linear combination, which correspond to three functions  $X_3^{(p)}$ ,  $p=1, 2, 3$ . The proof follows from the completeness of a 10-dimensional basis for class 2.

For  $\Psi$  of class 2 there are only 3 Lorentz invariant (Sventkovsky, 2004):

$$C^{(\pm 1)}\xi^{(\pm 1)}=F^{(\mp)}X^{(\pm)}, C^{(0)}\xi^{(0)}+C^{(0)}_0 X^{(0)}_0=F^{(3)}X^{(3)}+F^{(0)}_0 X^{(0)}_0=\Psi_A$$

The real part of the invariants  $\Psi^{(\pm)}=F^{(\mp)}X^{(\pm)}$  is obtained from the sum (difference) of the complex invariants, corresponds to the wave function of the electromagnetic field which has a zero projection of the (iso) vector operator  $J_k, J^{(n)}$  at each point of Minkowski space.

$$\Psi=\Psi_{EH}=EX^{(1)}+HX^{(2)}, \Psi_{HE}=-HX^{(1)}+EX^{(2)}, \langle\Psi|J_i|\Psi\rangle=0, \\ \langle\Psi|J^{(n)}|\Psi\rangle=0.$$

The Lorentz transformations  $X^{(k)}$  with the condition of Sommerfeld about the invariance of the wave function  $\Psi=E X^{(1)}+H X^{(2)}$ , provide the well-known Lorenz transformation properties of the fields  $E, H, A, A_0$ .

$$\Psi=\Psi_{EH}=EX^{(1)}+HX^{(2)}, \Psi_{HE}=-HX^{(1)}+EX^{(2)}, \langle\Psi|J_i|\Psi\rangle=0, \\ \langle\Psi|J^{(n)}|\Psi\rangle=0.$$

Mathematically the vectors can be added as objects having different directions, but in physics objects are always added as objects with one and the same

direction. For example, a physical object is a set of projections of a vector. The addition of vectors will be regarded as the addition of a set of unidirectional projections. A vector has one to one correspondence with a set of its projections and vice versa. The projections are directed to the center of the vector for positive values of the projections and from the center for negative values. The basic states of the fields  $E, H, A$  which are directed along the axis  $x_3$ , have the form:

$$X_3^{(1)}=-\sin\theta \cos\gamma, X_3^{(2)}=\sin\theta \sin\gamma, X_3^{(3)}=\cos\theta.$$

To visualize the model of basic states in the center of the local observer, imaginary sphere of unit radius  $X^{(3)}$  is introduced;  $i_\theta, i_\varphi, i_3$  are spherical orts, given:

$$X^{(1)}(\varphi, \theta, 0)=i_\theta, X^{(2)}(\varphi, \theta, 0)=i_\varphi, X^{(3)}(\varphi, 0, \gamma)=i_3.$$

The vector  $i_\theta$  is assigned to the projection of  $\cos\gamma$  on the sphere. The vector  $i_\varphi$  is assigned to the projection of  $\sin\gamma$  on the sphere. The vector  $i_3$  is assigned to the projection of  $\cos(\theta)$ , that are directed along  $i_r$ . Then replace the  $\cos\gamma$  on  $i_\theta$  in  $X^{(1)}$ ,  $\sin\gamma$  on  $i_\varphi$  in  $X^{(2)}$  and  $X^{(3)}=\cos(\theta)$  will be considered as a set of projections of  $i_3$ , directed along  $i_r$ . The resulting visual model of the electromagnetic fields, correspond to a basis states  $X_3^{(1)}, X_3^{(2)}, X_3^{(3)}$  and  $X_0^{(0)}$  shown in Figure 2.

The polarity of the vector of electric field, the axial symmetry of the vector of magnetic field has been reflected in this mode.  $E, H, A, A_0$  and  $X^{(1)}, X^{(2)}, X^{(3)}, X_0^{(0)}$  under the spatial inversion are transformed identically  $\hat{I} X^{(k)}=(-1)^k X^{(k)}$ .

### **The generalized Lorentz group in the angular and matrix representation for transformations of spinors, tensors**

The lie algebra of the groups Lorenz (Equation 5), Poincare (Equation 6) and its generators in the coordinate representation (Ohnuki, 1988);  $L=(M_{23}, M_{31}, M_{12})$ ,  $K=(M_{01}, M_{02}, M_{03})$ , where  $M_{ij}=x_i P_j - x_j P_i$ ,  $x_0=t$ , and  $P_i=-i\partial/\partial x_i$ ,  $P_0=i\partial/\partial t$  are operators of momentum and energy, have the form:

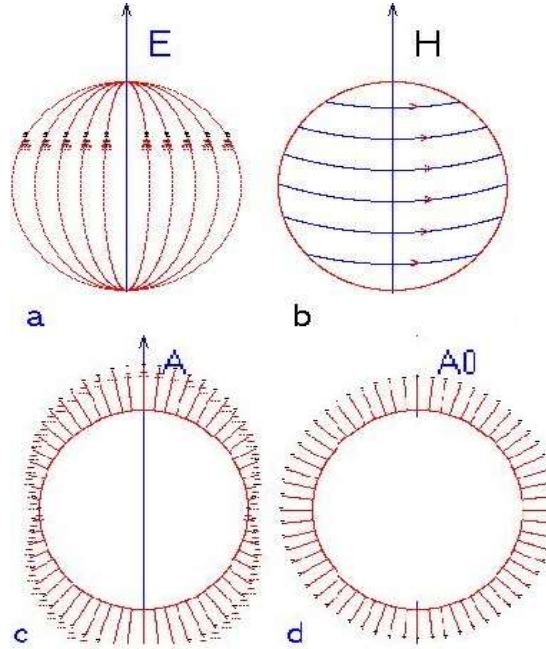
$$[L_i, L_n]=i\varepsilon_{ink} L_k, [K_i, L_n]=i\varepsilon_{ink} K_k, [K_i, K_n]=-i\varepsilon_{ink} L_k. \quad (5)$$

$$[P_i, P_k]=0, [K_k, P_k]=-i P_0, [L_i, P_n]=i\varepsilon_{ink} P_k, [K_i, P_0]=-i P_i. \quad (6)$$

Operators  $Q^{(p)}_k(\varphi, \theta, \gamma)$  have been introduced (Sventkovsky, 2004) in a symmetric form as a vector for the lower indices and an isovector for the upper indices, that is,

$$Q^{(p)}=i X^{(p)} \hat{J} + [X^{(p)} J], Q^{(p)}_k=i X^{(p)}_k \hat{J} + \varepsilon_{ink} X^{(p)}_i J_n = i X^{(p)}_k - \varepsilon_{inp} X^{(i)}_k J^{(n)}$$

$\hat{J}$  is a linear, differential scalar Lorenz invariant operator that has properties:  $\hat{J} \Psi=j \Psi$  for class  $2j$ . It is possible



**Figure 2.** The visual models of the electromagnetic fields that realizes the principle of superposition of states.  $\Psi^E = \sin\theta \mathbf{i}_\theta$ ,  $\Psi^H = \sin\theta \mathbf{i}_\phi$ ,  $\Psi^A = \cos\theta \mathbf{i}_r$ ,  $\Psi^{A0} = \mathbf{i}_r$ .

because the Wigner  $D^j$  function can be decomposed into a homogeneous polynomial of degree  $2j$  from  $\psi_k$  (Equation 2), (Varshalovich, 1975), example  $\hat{J}=1/2 \psi_k \partial/\partial\psi_k$ . Further, for the state of class  $2j$ , operator  $\hat{J}$  will be replaced by  $j$  everywhere. The operators  $Q$  for  $\Psi$  of class  $2j$  have the form:

$$\begin{aligned}
 Q^{(3)}_1 &= j \cos\varphi \sin\theta + i \cos\varphi \cos\theta \frac{\partial}{\partial\theta} - i \sin\varphi / \sin\theta \frac{\partial}{\partial\varphi} + i \sin\varphi \operatorname{ctg}\theta \frac{\partial}{\partial\gamma} \\
 Q^{(3)}_2 &= ij \sin\varphi \sin\theta + i \cos\varphi \sin\theta \frac{\partial}{\partial\theta} + i \cos\varphi / \sin\theta \frac{\partial}{\partial\varphi} - i \cos\varphi \operatorname{ctg}\theta \frac{\partial}{\partial\gamma} \\
 Q^{(3)}_3 &= ij \cos\theta - i \sin\theta \frac{\partial}{\partial\theta} \\
 Q^{(1)}_2 &= ij \cos\varphi \sin\gamma + ij \cos\theta \sin\varphi \cos\gamma - i \sin\varphi \sin\gamma \frac{\partial}{\partial\varphi} + i \cos\varphi \cos\gamma \frac{\partial}{\partial\gamma} - i \sin\varphi \cos\gamma \sin\theta \frac{\partial}{\partial\theta} \\
 Q^{(1)}_1 &= -ij \sin\varphi \sin\gamma + ij \cos\theta \cos\varphi \cos\gamma - i \sin\theta \cos\varphi \cos\gamma \frac{\partial}{\partial\theta} - i \cos\varphi \sin\gamma \frac{\partial}{\partial\varphi} - i \sin\varphi \cos\gamma \frac{\partial}{\partial\gamma} \\
 Q^{(1)}_3 &= -ij \sin\theta \cos\gamma - i \sin\gamma \operatorname{ctg}\theta \frac{\partial}{\partial\varphi} - i \cos\gamma \cos\theta \frac{\partial}{\partial\theta} + i \sin\gamma / \sin\theta \frac{\partial}{\partial\gamma} \\
 Q^{(2)}_1 &= -ij \cos\gamma \sin\varphi - ij \cos\theta \sin\varphi \cos\varphi + i \sin\varphi \sin\gamma \frac{\partial}{\partial\gamma} - i \cos\varphi \cos\gamma \frac{\partial}{\partial\varphi} + i \sin\gamma \cos\varphi \sin\theta \frac{\partial}{\partial\theta} \\
 Q^{(2)}_3 &= ij \sin\gamma \sin\theta + i \cos\gamma \sin\theta \frac{\partial}{\partial\theta} + i \cos\gamma / \sin\theta \frac{\partial}{\partial\varphi} - i \cos\gamma \operatorname{ctg}\theta \frac{\partial}{\partial\gamma} \\
 Q^{(2)}_2 &= ij \cos\varphi \cos\gamma - ij \cos\theta \sin\varphi \sin\gamma + i \sin\theta \sin\varphi \sin\gamma \frac{\partial}{\partial\theta} - i \cos\varphi \sin\gamma \frac{\partial}{\partial\gamma} - i \sin\varphi \cos\gamma \frac{\partial}{\partial\varphi}
 \end{aligned}$$

Under the action of the operator  $J, Q$  with upper and lower indices  $+, -$  and  $0$  on  $D^j_{m,m'}$  the indices  $m, m'$  can increase, decrease or remain unchanged (Sventkovsky, 2004).

Substituting the expression for  $Q^{(p)}, J$  we can verify that

$Q^{(p)}, J$  have the same Lie algebra (7) as the Lie algebra of the Lorentz group (Equation 5), where  $p=1,2,3$  corresponded to tree angular presentations (the spinor, tensor presentations) of the Lorentz group, that is,

$$[J_i, J_n] = i\epsilon_{ink} J_k, [Q^{(p)}_i, J_n] = i\epsilon_{ink} Q^{(p)}_k, [Q^{(p)}_i, Q^{(p)}_n] = -i\epsilon_{ink} J_k \quad (7)$$

The Lorentz transformation  $v = |v|x_3$  with the (boost) generator  $Q^{(3)}_3, p=3$  is independent of  $\varphi$  and  $\gamma$  and is symmetrical with respect to two observers  $X_3$  and  $X^{(3)}$ , hence  $\varphi' = \varphi, \gamma' = \gamma, \operatorname{th}(\chi) = v/c$  (13).

$$\exp(-i Q^{(3)}_3) \begin{pmatrix} X^{(3)}_3 \\ X^{(0)}_0 \end{pmatrix} = \begin{pmatrix} \operatorname{ch}(\chi) & \operatorname{sh}(\chi) \\ \operatorname{sh}(\chi) & \operatorname{ch}(\chi) \end{pmatrix} \begin{pmatrix} X^{(3)}_3 \\ X^{(0)}_0 \end{pmatrix},$$

$$\begin{pmatrix} x_3 \\ t' c \end{pmatrix} = \begin{pmatrix} \operatorname{ch}(\chi) & \operatorname{sh}(-\chi) \\ \operatorname{sh}(-\chi) & \operatorname{ch}(\chi) \end{pmatrix} \begin{pmatrix} x_3 \\ t c \end{pmatrix}$$

The Lorenz transformations in Minkowski space and in the space of orientations respectively of four-dimensional vectors  $\mathbf{A}, \mathbf{A}_0$  and  $\mathbf{X}^{(3)}, \mathbf{X}^{(0)}$ , bivectors  $\mathbf{E}, \mathbf{H}$  and  $\mathbf{X}^{(1)}, \mathbf{X}^{(2)}$ , as well as spinors  $\mathbf{C}$  and  $\psi = \xi^{(tj)}$  are opposite, inverse to each other, but the transformations of the vectors under the spatial rotation are the same. This ensures fulfillment of Sommerfeld condition about Lorentz invariance:

$$\begin{aligned}
 \Psi_A &= \mathbf{A}X^{(3)} + \mathbf{A}_0 X^{(0)}_0 c \\
 \Psi_{EH} &= \mathbf{E}X^{(1)} + \mathbf{H}X^{(2)}, \quad \Psi = \psi \mathbf{C}.
 \end{aligned}$$

The Lorentz transformation for angular variables which was obtained earlier directly follows from the Lorentz transformations of spinors:

$$\xi_m^{(\pm i)} = \exp(-i \chi Q^{(3)}) \xi_m^{(\pm i)}, \text{ or } \xi_m^{(\pm i)} = \exp(\pm i \chi m) \xi_m^{(\pm i)},$$

$$C_m = \exp(\mp m \chi) C_m, \quad \exp(\chi) = \sqrt{(1 + V/c)/(1 - V/c)},$$

$$\text{tg}(\theta'/2) = \exp(-\chi) \text{tg}(\theta/2).$$

These transformations of angles correspond to the known transformation of angles for polarized light with direction velocity along the axis  $X^{(3)}$  and velocity  $v' = -v$ , (Pauli, 1958).

The Casimir operators of the Lorentz group in angular representations are operators  $\mathbf{J}^2 - \mathbf{Q}^{(3)2}$ ,  $\mathbf{J}, \mathbf{Q}^{(3)}$  have been obtained from the Casimir operators  $\mathbf{K}^2 - \mathbf{L}^2, \mathbf{L}, \mathbf{K}$  of the Lorentz group by replacing the generators of the Lorentz group  $\mathbf{L}, \mathbf{K}$  by  $\mathbf{J}, \mathbf{Q}^{(3)}$ . The irreducible representations of the Lorentz group are characterized by a pair of numbers corresponding to the eigenvalues of the operators  $Z_{\pm}^2$  where  $\mathbf{Z}_{\pm} = (\mathbf{J} \pm i \mathbf{Q}^{(3)})/2$ ,  $[Z_{\pm}, Z_{\pm}] = i Z_{\pm}$ ,  $[Z_{+}, Z_{-}] = 0$ .

The spinors  $\xi^{(j)}$ ,  $\xi^{(-j)}$  are transformed, respectively on irreducible representation  $(j, 0)$  and  $(0, j)$ , because  $Z_{+}^2 \xi^{(j)} = j(j+1) \xi^{(j)}$ ,  $Z_{-}^2 \xi^{(j)} = 0$ ,  $J_k \xi^{(\pm i)} = \xi^{(\pm i)} S_k$ ,  $Q^{(3)} \xi^{(\pm i)} = \pm i \xi^{(\pm i)} S$ .

The matrix representations of these two-irreducible spinor representation of the Lorentz group for an arbitrary  $j$  can be obtained from (7),  $p=3$  by replacing the operators  $J_k, Q^{(3)}$  on their matrix representations in the spinor basis  $j$ ,  $\psi = \xi^{(j)T}$  or  $\psi = \xi^{(j)T}$ , as  $\langle \psi^T | Q^{(3)}_k | \psi \rangle$ .

The elements of  $\xi_m^{(\pm i)}$  whose Lorentz transformation has no an additional component are the eigenfunctions of  $Q^{(3)}_3$ .

$$Q^{(3)}_3 \xi_m^{(\pm i)} = \pm i m \xi_m^{(\pm i)}, J_3 \xi_m^{(\pm i)} = m \xi_m^{(\pm i)}$$

The bivectors  $X^{(-)}, X^{(+)}$  are transformed respectively on irreducible representations  $(1, 0)$  and  $(0, 1)$  of the Lorentz group, because  $Z^{(\pm)2} X^{(-)} = X^{(-)}(1 \pm 1)$ . The four-vector  $X^{(3)}$  and  $X^{(0)}$  is transformed on irreducible representation  $(1/2, 1/2)$ , because  $Z^{(\pm)2} X^{(3)} = 3/4 X^{(3)}$ . Thus, the representation of the Lorentz group (Equation 7) for the class 2 in 10-dimensional basis  $\psi = X^{(i)}_n$  splits into irreducible vector representations for the basis  $X^{(3)}$  and  $X^{(0)}$  and into adjoint representation for the real basis  $\mathbf{X}^{(1)}$  and  $\mathbf{X}^{(2)}$ .

**Definitions**

The Generalized Lorentz group (Equations 1, 7 and 8) is the group consists of 16 generators  $\hat{J}$ ,  $J_n$ ,  $J^{(k)}$  and  $Q^{(n)}_k$  which was obtained by combining the known angular representation of the Lorentz group (Equation 7) (Sventkovsky, 2004) and its transposed angular representation.

$$[Q^{(n)}_i, Q^{(p)}_k] = i \delta_{ik} \epsilon_{npm} J^{(m)} - i \delta_{np} \epsilon_{ikn} J_n, [Q^{(i)}_p, J^{(n)}] = i \epsilon_{ink} Q^{(k)}_p \quad (8)$$

The generalized group provides symmetry between the

representation and transpose representation of the group or between the vector rotations of the original local observer and the isovector rotations of the rotated local observer, it is illustrated in Figure 3. The symmetry operator  $W$  retains the invariance of the Lie algebra of the generalized Lorentz group  $Q^{(n)}_k = (-1)^{(k+n)} W Q^{(k)}_n$ .

Matrix representations of the generators of the generalized Lorentz group (Equations 1, 7 and 8) in the basis bi-spinor,  $j=1/2$  corresponding the replacement of  $J_n, J^{(k)}, Q^{(n)}_k, \hat{J}$  by  $S^{(0)}_n, S^{(k)}, S^{(0)}_k, S^{(n)}$ ,  $j$  matches 16 basis elements of the full Clifford algebra formed from Dirac's gamma matrices (Fluge, 1974). The proof uses identities:

$$J_n \psi = \psi S^{(0)}_n, J^{(k)} \psi = \psi S^{(k)}, [S^{(k)}, S^{(n)}] = -i \epsilon_{kn p} S^{(p)},$$

$$Q^{(n)}_k \psi = 2i J^{(n)} J_k \psi = \psi 2i S^{(n)} S^{(0)}_k, 2J^{(3)} \psi = \psi g_4, 2J^{(1)} \psi = \psi g_0,$$

$$2J^{(2)} \psi = \psi \hat{g}_0, 2Q^{(2)} \psi = \psi g, 2Q^{(1)} \psi = \psi \hat{g}, \langle \psi^T | J_k | \psi \rangle = S^{(0)}_k$$

Where  $g_0, g$  and  $\hat{g}_0, \hat{g}$ -gamma Dirac matrices in the Weyl basis

$$g_0 = \begin{pmatrix} 0 & \sigma_0 \\ \sigma_0 & 0 \end{pmatrix}, g = \begin{pmatrix} 0 & -\sigma \\ \sigma & 0 \end{pmatrix}, g_4 = \begin{pmatrix} \sigma_0 & 0 \\ 0 & -\sigma_0 \end{pmatrix}, \hat{g}_0 = i \begin{pmatrix} 0 & \sigma_0 \\ -\sigma_0 & 0 \end{pmatrix}, \hat{g} = -i \begin{pmatrix} 0 & \sigma \\ \sigma & 0 \end{pmatrix},$$

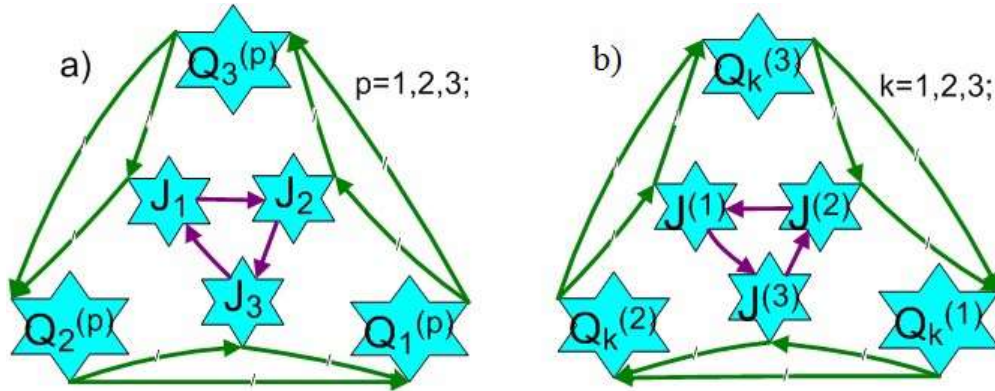
$$S^{(0)}_{\pm} = \begin{pmatrix} \sigma_{\pm} & 0 \\ 0 & \sigma_{\pm} \end{pmatrix}, S^{(3)} = 1/2 \begin{pmatrix} \sigma_0 & 0 \\ 0 & -\sigma_0 \end{pmatrix}, S^{(2)} = 1/2 \begin{pmatrix} 0 & i\sigma_0 \\ i\sigma_0 & 0 \end{pmatrix}, S^{(1)} = 1/2 \begin{pmatrix} 0 & \sigma_0 \\ \sigma_0 & 0 \end{pmatrix}, \quad (7)$$

The infinitesimal generator of the Lorentz group  $L_k$  and  $K_p$  (Ohnuki, 1988) are identical to matrices  $\langle \psi^T | J_k | \psi \rangle$ ,  $\langle \psi^T | Q^{(3)}_n | \psi \rangle$  by using the basis  $\psi = (X^{(0)}_0, X^{(3)}_1, X^{(3)}_2, X^{(3)}_3)$ . This can be easily checked using (13). The study can also verify that ten generators of the Poincare group in angular (spinor) representation  $J, Q^{(3)}, Q^{(-)}, i J^{(-)}$ , for  $p=3$ , which were obtained using the generators of the generalized Lorentz group, have the same Lie algebra (Equations 5 and 6) of the ten generators of the Poincare group  $L, K, P$  and  $P_0$ , where  $Q^{(-)} = Q^{(1)} + i Q^{(2)}$ . Four-dimensional vector  $(P^{(-)}, P^{(-)}_0) = (Q^{(-)}, i J^{(-)})$  can be regarded as analogous to the momentum operator in the Lie algebra of angular variables, since they have the same Lie algebra as Poincare group. It is illustrated in Figure 4.

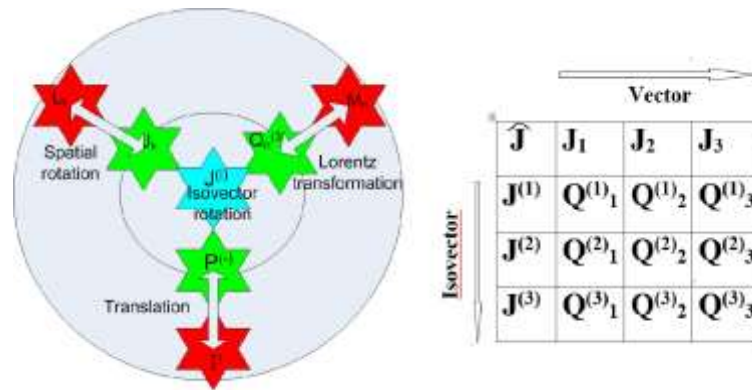
The study can also verify using the Baker-Campbell-Hausdorff formula that generators of the Poincare group in angular representation have the known transformation properties under the Lorentz transformation,  $(J, Q^{(3)})$  transformed as bivector,  $(Q^{(-)}, i J^{(-)})$  transforms as four-vector momentum,  $J^{(3)}$  transform as scalar. Generalized Lorentz group is realized in the space of orientations.

The Pauli-Lubanski vector in the operator angular representation has the equivalent form  $\hat{W}_0 = (P, J)$ ,  $\hat{W} = P_0 J - [P, Q^{(3)}]$  that is obtained from Pauli-Lubanski vector by replacing the matrices  $L$  and  $M$  by the operators  $J, Q^{(3)}$ . The operators  $\hat{W}_0$  and  $\hat{W}$  in the matrix representation  $J, Q^{(3)}$  in the corresponding basis is identical to the original Pauli-Lubanski vector.

The second Casimir operator of the Poincare group for the seven-dimensional space has the equivalent form  $(\hat{W}_0^2 - \hat{W}^2)$  that is obtained from the second Casimir operators by replacing the Pauli-Lubanski vector by Pauli-Lubanski vector in angular representation.



**Figure 3.** The Lie algebra of the generalized Lorentz group (a, b). (a) is a group of external symmetry three representations of the Lorentz group (in the space of orientations), (b) is a group of internal symmetry, three representations of the transpose Lorentz group.



**Figure 4.** The relationship between Poincare group in different representations and transpose group of rotation that is considered as the group of internal symmetry  $J^{(k)}$ .

**The generalized Dirac, Maxwell, Weyl equations**

The operator part of the Poincare invariant equations for the wave function which has the momentum operators in the first degree are invited to express in symmetric form an equal to the scalar product of two four-dimensional vectors of the momentum operators for space-time and for space of the orientations. We have:  $N^{(\pm)} = P^{(\pm)} P - P^{(\pm)}_0 P_0$  where  $N^{(\mp)} = N^{(1)} \pm i N^{(2)}$  is complexified operator, below used real invariant operators:

$$N^{(1)} = Q^{(1)} P + J^{(2)} P_0 / c, \quad N^{(2)} = Q^{(2)} P - J^{(1)} P_0 / c.$$

Thus Poincare invariant equations for the wave function can consist of two equations have different spatial parities corresponding to an even operator:

$N^{(1)} = \hat{P} \hat{N}^{(1)}$  and an odd operator  $N^{(2)} = -\hat{P} \hat{N}^{(2)}$ . These equations will be referred to as the generalized Dirac,

Maxwell, Weyl equations.

The generalized Maxwell equations for the class  $2j=2$ , describing the spinless state and its analogue have the form (Equations 9 and 10):

$$\Psi = EX^{(1)} + HX^{(2)}, \quad \langle \Psi | J_i | \Psi \rangle = 0, \quad \langle \Psi | J^{(k)} | \Psi \rangle = 0$$

$$N^{(1)} \Psi = 4\pi \Psi_C \tag{9}$$

$$N^{(2)} \Psi = 0. \tag{10}$$

where  $\Psi_C = iX^{(3)} + I_0 cX^{(0)}$ ,  $I = (I_1, I_2, I_3)$  is vector density of electric current,  $I_0$  is the density of the electric charge.

Representation of generalized Maxwell Equations (9) and (10) in the basis  $X^{(k)}_n$  are equivalent to the Maxwell equations

$$[PH] + P_0 E / c = -i4\pi / c I, \quad (PE) = -i4\pi I_0, \tag{11}$$

$$[PE] - P_0 H / c = 0, \quad (PH) = 0. \tag{12}$$

For proof, we substitute in (9.10) the form  $\Psi$ ,  $N^{(1)}$  and  $N^{(2)}$  and use identity:

$$J^{(i)}X^{(n)}_p = i\varepsilon_{ink}X^{(k)}_p, \quad Q^{(n)}_k X^{(0)}_0 = ij X^{(n)}_k, \quad (13)$$

$$J_i X^{(p)}_n = i\varepsilon_{ijk} X^{(p)}_k, \quad Q^{(m)}_i X^{(p)}_n = i\delta_{i,n}\delta_{m,p}X^{(0)}_0 + i\varepsilon_{ink}\varepsilon_{mpd} X^{(d)}_k. \\ (\mathbf{Q}^{(1)}\mathbf{P} + J^{(2)}P_0/c)\Psi = (i[\mathbf{PH}] + iP_0\mathbf{E}/c)\mathbf{X}^{(3)} + i(\mathbf{PE})X^{(0)}_0 = 4\pi(\mathbf{IX}^{(3)} + I_0 X^{(0)}_0). \\ (\mathbf{Q}^{(2)}\mathbf{P} - J^{(1)}P_0/c)\Psi = (-i[\mathbf{PE}] + iP_0\mathbf{H}/c)\mathbf{X}^{(3)} + i(\mathbf{PH})X^{(0)}_0 = 0.$$

Equating to zero the coefficients in Equation 9 and 10 at each of the bases  $X^{(3)}_k$  and  $X^{(0)}_0$ , we obtained, respectively, a second (Equation 11) and a first pair of Maxwell's equations (Equation 12).

The normalization of the wave function in the double space of orientations (over the angles) at the point  $x_1, x_2, x_3$ , is equal to the energy density of the electromagnetic field:  $b^2 \langle \Psi_{EH} | \Psi_{EH} \rangle / (8\pi) = (E^2 + H^2) / (8\pi)$ .

The Poynting vector are written in the form:

$$-i c b^2 \langle \Psi_{EH} | \mathbf{Q}^{(3)} | \Psi_{EH} \rangle / (8\pi) = c[\mathbf{EH}] / (4\pi),$$

The generalized Dirac equation  $j=1/2, 1, 3/2, \dots$  have the form (Equations 14 or 15). Representation (Equations 14 or 15) in the basis,  $j=1/2, (2)$  coincide respectively with the ordinary Dirac equations (Equations 16) for the electron  $\Psi = \psi C$  or with the Dirac equations (Equation 17) for the unknown particles  $\Psi^\Lambda = \psi \hat{C}$ ,  $m_e$  is the mass.

$$N^{(2)} \Psi = m_e c / (2h) \Psi \quad (14) \\ N^{(1)} \Psi^\Lambda = m_e c / (2h) \Psi^\Lambda \quad (15)$$

For proof, we substitute in (Equations 14 and 15) the form of  $N^{(1)}, N^{(2)}$ ,  $\psi = (\psi_1, \psi_2, \psi_3, \psi_4)$ , (2). and using the identities  $N^{(2)}\psi = \psi(\mathbf{g}\mathbf{P} - g_0 P_0/c)$ ,  $2N^{(1)}\psi = \psi(\hat{\mathbf{g}}\mathbf{P} - \hat{g}_0 P_0/c)$ .

Equating to zero the coefficients at each from the bases  $\psi_k$  in (Equations 14 and 15), identically we obtain equation Dirac in chiral representation with matrices, respectively  $\mathbf{g}, g_0$  (Ryder, 1987), (16) and  $\hat{\mathbf{g}}, \hat{g}_0$ , (Ryder, 1987):

$$(\mathbf{g}\mathbf{P} - g_0 P_0/c + m_e c/h) C = 0. \quad (16)$$

$$(\hat{\mathbf{g}}\mathbf{P} - \hat{g}_0 P_0/c + m_e c/h) \hat{C} = 0. \quad (17)$$

The spinor Lorentz transformation of the  $N^{(2)}$  when using a basis  $\psi = (\psi_1, \psi_2, \psi_3, \psi_4)$  corresponds to the transformation group  $SL(2, C)$ , relativistic spin group:

$$\psi' = \psi U, \quad U^{-1} \langle \psi^{*T} N^{(2)} \psi \rangle U = U^{-1} (gP - g_0/c P_0) U, \quad \psi = (\xi^{(1/2)T}, \xi^{(-1/2)T}) \\ U^{-1} (\mathbf{g}\mathbf{P} - g_0/c P_0) U = \mathbf{g}'\mathbf{P}' - g'_0/c P'_0,$$

$U^{-1} = U^{*T}$  space rotation,  $\xi^{(\pm 1/2)}_m' = \exp(\pm m \chi) \xi^{(\pm 1/2)}_m$  for Lorentz rotation.

Solution of these Equations 14 and 15 for a particle at rest, assuming that the term with the momentum operator

$P$  vanish, correspond to standard representation of basis and has the form:

$$-J^{(1)}P_0/c \Psi = m_e c / (2h) \Psi, \quad J^{(1)}\Psi = \mp \Psi / 2 \quad (18)$$

$$J^{(2)}P_0/c \Psi^\Lambda = m_e c / (2h) \Psi^\Lambda, \quad J^{(2)}\Psi^\Lambda = \pm \Psi^\Lambda / 2 \quad (19)$$

Decisions have a zero balance between left and right

$$\Psi = C(\xi^{(1/2)} \mp \xi^{(-1/2)}), \quad \Psi^\Lambda = \hat{C}(\xi^{(1/2)} \pm \xi^{(-1/2)}), \\ \langle \Psi | J^{(3)} | \Psi \rangle = 0, \quad \langle \Psi^\Lambda | J^{(3)} | \Psi^\Lambda \rangle = 0.$$

At the inner inversion, electron becomes the positron (Equations 16, 18 and 20) and on the contrary, but the unknown particle remains unknown particle (Equation 17, 19 and 21):

$$\hat{I}(\xi^{(1/2)} \mp \xi^{(-1/2)}) = \pm(\xi^{(1/2)} \mp \xi^{(-1/2)}) \quad (20)$$

$$\hat{I}(\xi^{(1/2)} \pm \xi^{(-1/2)}) = \pm i(\xi^{(1/2)} \pm \xi^{(-1/2)}) \quad (21)$$

Generalized Weyl equation with spin  $j=1/2$  for Lorentz invariant  $\Psi^{(\pm)} = C^{(\pm)} \xi^{((\pm 1/2))}$  is identical to the Weyl equation (Akhiezer and Berestetskii, 1965), for right or left neutrinos, have view:

$$N^{(\pm)} \Psi^{(\mp)} = 0, \text{ or, } (-P_0 c \pm \mathbf{P} \boldsymbol{\sigma}) C^{(\pm)} = 0. \quad (22)$$

Balance for the state  $\Psi^{(\pm)}$  between left and right violated, as  $J^{(3)}\Psi^{(\pm)} = \pm \Psi^{(\pm)} / 2$ .

### Theorem 2

Mirror symmetry of basis states with spin  $j=1/2$ . The mirror basis  $\mu^{(\pm 1/2)} = \xi^{((1/2))} \mp i \xi^{((-1/2))}$  is unique. No other bases with this property exist. This basis is not changes under the inversion  $\hat{I} \mu^{(\pm 1/2)} = \pm i \mu^{(\pm 1/2)}$ .

The proof follows from the completeness set of the basis and the choice of a basis in the form of linear combinations of basis  $\xi^{((1/2))}$  and  $\xi^{((-1/2))}$ .

### Theorem 3

Mirror antisymmetry of basis states with spin  $1/2$ . There is a subgroup of transformations  $\eta^{(1/2)} = \cos(\beta/2) \xi^{(1/2)} - \sin(\beta/2) \xi^{(-1/2)}$ ,  $\eta^{(-1/2)} = \sin(\beta/2) \xi^{(1/2)} + \cos(\beta/2) \xi^{(-1/2)}$  for any  $\beta$ , when the bases are transformed into each other under inversion  $\hat{I} \eta^{(\pm 1/2)} = \pm \eta^{((\mp 1/2))}$ .

The proof is similar. Thus, there is a plurality of bases having mirror antisymmetry property  $\eta^{(\pm 1/2)}$ , but there is only one basis with mirror symmetry property  $\mu^{(\pm 1/2)}$ . It is additionally assumed that particles in rest with a nonzero mass have a zero balance between the left and the right  $\langle \eta^{(\pm 1/2)} | J^{(3)} | \eta^{(\pm 1/2)} \rangle = 0$  which is implemented for  $\beta = \pi/2$ .

The symmetry of Maxwell's equations when  $(\mathbf{E}, \mathbf{H})$  is

replaced by  $(-\mathbf{H}, \mathbf{E})$  is called the electromagnetic duality. In general, there is a Heaviside-Larmor-Raynicha subgroup (HLR) (Konopelchenko, 1977):

$$\mathbf{E}' = \mathbf{E} \cos(\alpha) + \mathbf{H} \sin(\alpha), \mathbf{H}' = -\mathbf{E} \sin(\alpha) + \mathbf{H} \cos(\alpha).$$

These transformations correspond to the turn of the rotated local observer about axis  $X^{(3)}$  by angle  $\alpha$  or to  $\Psi' = \exp(i\alpha J^{(3)}) \Psi$ ,  $\gamma' = \gamma + \alpha$  in the framework transformations of generalized Lorentz group. Example, the use of the invariance of  $\Psi' = \Psi$  and  $\Psi = \mathbf{E}\mathbf{X}^{(1)} + \mathbf{H}\mathbf{X}^{(2)}$ ,  $\alpha = \pi/2$ ,  $X^{(1)}(\gamma) = -X^{(2)}(\gamma + \pi/2)$ ,  $X^{(2)}(\gamma) = X^{(1)}(\gamma + \pi/2)$  are obtained conversion, yields transformations  $\mathbf{H}' = -\mathbf{E}, \mathbf{E}' = \mathbf{H}$ . The transformations preserve balance between the left and right  $\langle \Psi' | J^{(3)} | \Psi' \rangle = 0, \langle \Psi | J^{(3)} | \Psi \rangle = 0$ .

The transformation  $\gamma' = \gamma + \pi/2$  leads to transition into each other operators  $N^{(1)}, N^{(2)}$  that is  $N^{(1)}(\gamma) = -N^{(2)}(\gamma + \pi/2)$ ,  $N^{(2)}(\gamma) = N^{(1)}(\gamma + \pi/2)$ .

In this case the mirror anti-symmetry of particles is replaced by the mirror symmetry and vice versa. The particle with mirror antisymmetry under inner inversion and spatial inversion, converted into antiparticle, but particle with a mirror symmetry  $j=1/2$  converted into itself, that is, not converted to the antiparticle (Equations 14 and 15), as  $\hat{P}N^{(2)} = -N^{(2)}$  and  $\hat{P}N^{(1)} = N^{(1)}$ .

Transformation  $\gamma' = \gamma + \pi/2$  of the generalized Dirac equation for the electron (Equations 14 and 16) leads to the generalized Dirac equation for the unknown particles (Equations 15 and 17) and vice versa.

Transformation  $\gamma' = \gamma + \pi/2$  of the generalized Maxwell equations leads to the following changes: Maxwell's generalized equations (9 and 10) are replaced by Maxwell's generalized equations (24 and 25) that describe the existence of only magnetic charge: Equation 9 is replaced by Equation 24 and Equation 10 is replaced by Equation 25, with renaming electric charge (Equation 9) as magnetic charge (Equation 24) and renaming zero magnetic charge (Equation 10) as zero electric charge (Equation 25). Thus:

$\Psi_C = i\mathbf{X}^{(3)} + I_0 c X^{(0)}$  is replaced by  $\Psi_M = I_M \mathbf{X}^{(3)} + I_{M0} c X^{(0)}$  because  $X^{(3)}(\gamma) = X^{(3)}(\gamma + \pi/2)$ .

$$N^{(2)} \Psi = 4\pi \Psi_M. \tag{23}$$

$$N^{(1)} \Psi = 0. \tag{24}$$

Matrix representations (Equations 23 and 24), when (Equation 13) is used, are identical to the Maxwell equations only in the case of existence of the magnetic charge.

Given the unified nature of the spin states for all  $j$ , the uniform representation of the equations of Dirac and Maxwell in the form of the generalized equations of Dirac and Maxwell whose matrix representations coincide with Dirac's and Maxwell's equations, as well as because the magnetic monopole is an consequence of the existence

of duality symmetries in electrodynamics, the following axiom is proposed:

The transformation  $\gamma' = \gamma + \pi/2$  of the generalized Dirac equation and the generalized Maxwell equations leads to the same results. In other words, it is the transformation that implements the dual symmetry (generalized) of the Dirac equation and Maxwell's equations in the exchange of electric and magnetic charges. That is, a particle with electric charge (electron) is replaced by a particle with magnetic charge. Hence the unknown particles (Equations 15 and 19) are the Dirac monopole. The results are shown in Figure 5.

The transformation  $\gamma' = \gamma + \pi$  corresponding to rotation about axis  $X^{(3)}$  by angle  $\pi$  leads to a change in sign of the operators  $N^{(1)}, N^{(2)}$  which corresponds to a change of sign of the mass of particles (Equations 14 and 15), that is replacement of electron or monopole on antiparticle (Figure 5).

In nature, there are no elementary particles with spin  $j > 1/2$  which correspond to the generalized Dirac equation with non-zero mass and, as their should to be presented only in the basis  $\xi^{(\pm)}$  which has no extended component under the Lorentz transformations. Given the nature of the ladder operators in the generalized Dirac equation for  $\xi^{(\pm)}$ , one can immediately see that such solutions do not exist.

### Superconductivity

The known relationship  $\mathbf{H} = i[\mathbf{P}\mathbf{A}], \mathbf{E} = iP_0\mathbf{A}/c - i\mathbf{P}\mathbf{A}_0$  between the vector potential of magnetic field, potential of electric field and fields  $\mathbf{E}, \mathbf{H}$ . is identical to equation  $N^{(1)} \Psi_A = \Psi_{EH}$ ,  $\Psi_A = \mathbf{A}\mathbf{X}^{(3)} + A_0 c X^{(0)}$  and  $\Psi_{EH} = \mathbf{E}\mathbf{X}^{(1)} + \mathbf{H}\mathbf{X}^{(2)}$ .

The generalized Dirac equation (Equation 25) of class 2 for Lorentz invariant  $\Psi = \Psi_{EH} + 1/\Lambda \Psi_A$ , where  $\Lambda$  is the constant length, using (Equation 13), splits into two equations for  $\Psi_{EH}, \Psi_A$

$$N^{(1)} \Psi = 1/\Lambda \Psi. \tag{25}$$

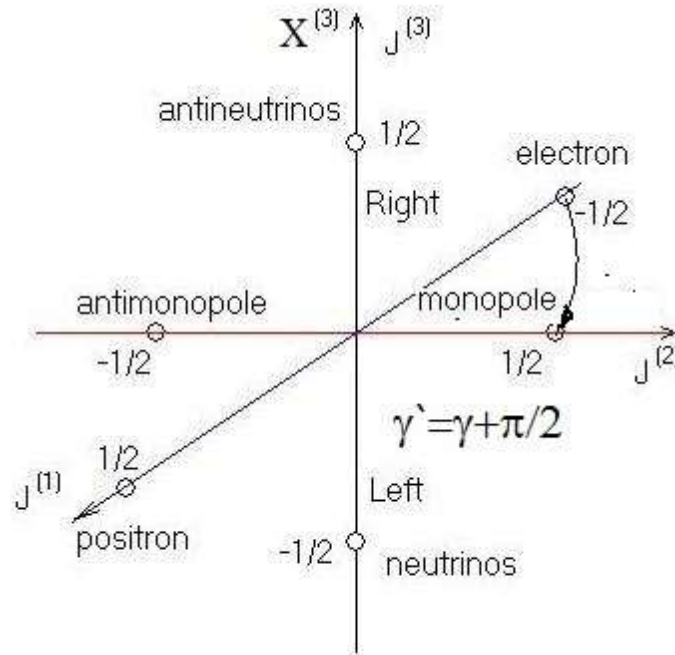
or  $(N^{(1)} \Psi_{EH} = -\Psi_A/\Lambda^2, N^{(1)} \Psi_A = \Psi_{EH})$ .

First equation is identical to the Maxwell equations (Equations 11 and 9) if it is denoted by  $\mathbf{j}_s = -\mathbf{A}c/(4\pi^2)$ ,  $j_{0s} = A_0/(4\pi^2)$  as the electric current. This corresponds to the first London equation for superconductivity where  $\Lambda$  is the depth of penetration,  $2h/(\Lambda c)$  can be associated with the mass of a heavy virtual photon.

The generalized Maxwell equations whose representation are equivalent to the Maxwell equations (Equations 11 and 12) and describe a just right state or only left state with analog spin or chirality  $\pm 1$ , have the following form:

$$N^{(1)} \Psi^{(\pm)} = 4\pi \Psi_C, N^{(2)} \Psi^{(\pm)} = \mp i 4\pi \Psi_C, \Psi^{(\pm)} = F(\mp) X^{(\pm)}, J^{(3)} \Psi^{(\pm)} = \pm \Psi^{(\pm)}, b^2 \langle \Psi^{(\pm)} | \mathbf{J} | \Psi^{(\pm)} \rangle = \pm 4[\mathbf{E}\mathbf{H}].$$





**Figure 5.** An analogue of the spin projection of  $J^{(k)}$  for a rotated local observer for particles with spin  $j=1/2$ , for an electron or a monopole at rest, for a neutrino flying at the speed of light.

The proof is similar. The spins of the left and the right states are opposite to one another. The existence of high-temperature superconductivity is probably due to exchange of spin of the electromagnetic field in the chiral state and the orbital moment.

**Conclusion**

In the isotropic Minkowski space, the multicomponent wave function  $C_k |k\rangle$  corresponding to the spin, vector states equivalently is described by a one-component wave function  $C_k \psi_k$  that depends on the position  $x_1, x_2, x_3, t$  and the orientation  $\varphi, \theta, \gamma$  of the local rotated observer. This corresponds to the replacement of the matrix basis  $|k\rangle$  by an operator basis  $\psi_k$ , that depends only on  $\varphi, \theta, \gamma$  with the same transformation properties as for the matrix basis.  $\varphi, \theta, \gamma$  may be interpreted as the possible orientation of the particle. Any angular dimensions (not are tied) does not depend on a specific spatial point since they are the same for all points of the space  $x_1, x_2$  and  $x_3$ .

For a unified description of states with spin  $j$ , vector and tensor fields dependent on the orientation of the meter, a state of a class  $2j$  was introduced as a class of functions  $\Psi = \psi C$  which may be represented by a homogeneous polynomial of degree  $2j$  of  $D^{(1/2)}_{m,m}$ .

The known difficulties associated with the ambiguity of the transformations under the imbedding of a new space into the Minkowski space (Cartan, 1927) were

successfully overcome by considering a well-known class of functions  $2j$ , (describing spinors, tensors) invariant under the Lorentz transformation and after determining the operators of the Poincare group for it in the angular representation.

The Lorentz group in matrix representation was essentially expanded to the generalized Lorentz group due to the inclusion in it of transposed representations the Lorentz group, namely: Generators of two well-known groups in the angular representation corresponding to the rotation group  $SU(2), J_n$  and the transposed rotation group  $SU(2), J^{(k)}$  and also the generators of the Lorentz group  $Q^{(p)}$  for different angular representations  $p=1,2$  and 3 form a generalized Lorentz group.

The symmetry of the generalized Lorentz group consists in its invariance with respect to the transpose operation in the matrix representation (or under the action of the operator  $W$ ) and corresponds to the symmetry between the original observer and the rotated local observer.

The generalized Lorentz group besides transformations associated with the Lorentz group has an additional degree of freedom which can be considered as the transformations of internal symmetry. If the operators of the group  $Q^{(p)}, J$  are in correspondence with the operators of the group  $K, L$  in the Lorentz transformation, then the operators  $J^{(k)}$  in the generalized group do not have such correspondence,

$J^{(k)}$  can be regarded as a generator group of the internal symmetry of particles, fields,  $\Psi$  (Figure 4). The

spin projection and the directions of the vector field are invariant under transformation by means of  $J^{(k)}$ . Spinors and vectors are always transformed into spinors and vectors under transformations  $J^{(k)}$ . The generalized Lorentz group in the angular representation has been obtained by combining the internal symmetry group  $J^{(k)}$  and the group of external symmetry with generators  $Q^{(p)}$  and  $J$  corresponding to the Lorentz group in the angular representation.

Inversion of space is always accompanied by a corresponding transformation of internal dimensions. Internal inversion: Transformation of  $\Psi$  in the mirror state can be obtained via (continuous) rotation using the generator  $J^{(k)}$  within the framework of transformations of the generalized group that preserve the invariance of the Lie algebra of the Lorentz group in angular representation. Therefore, the generalized Lorentz group, when spinors and vectors are transformed, includes the full Lorentz group. This fact partly explains that the parameter space for the SU(2) and SO(3) are different from each other twice.

Main laws nature equation of Dirac, Maxwell is like clockwork. All objects, wave function are moved, are transformed only with using generators of group, but do not move themselves. All objects can be moved over short distances with almost no distortion, but only objects that are eigenfunctions of generators (generalized) group. Figure 5 can be moved with the help of those generators without distortion on any distances. For example there is an identity:  $\exp(iaP_n) \exp(ikx_n) = \exp(ik(x_n+a))$ .

To obtain the first-degree equation on momentum, Dirac introduced a four-dimensional vector (from gamma matrices) independent of the coordinates.

Similarly the article introduces a four-dimensional vector  $P^{(+)}_k$  from the new angular dimensions that do not depend from the coordinates of space-time.

The simplest equations of nature must be first-degree differential equations with respect to dimensions and to be Poincare invariant. For this purpose it is advisable to use the Casimir operator  $P_k$  and  $P_k$  of the Poincare group in which one of the two momentum operators is replaced by the momentum operator in the angular representation which is unique for  $p=3$ . As a result two real Lorentz invariants  $N^{(1)}, N^{(2)}, P_k P^{(+)}_k = N^{(1)}$ ;  $N^{(2)}$  have been obtained.

These operators correspond to the first Casimir operators for the seven-dimensional space and have been used to obtain Dirac, Maxwell, Weyl equations. The matrices, bases were equivalently replaced by operators, basis functions with the same transformation properties, when introducing angular dimensions. The generators of the Poincare group in the angular representation have been used to obtain the Dirac matrices and the resulting matrix at the momentum operator in the matrix form of Maxwell's equations.

Generalized equation Dirac and Maxwell have two forms of representation  $N^{(1)}, N^{(2)}$  which correspond to different parity at the spatial inversion. There are good

reasons to believe that there are no other Poincare invariants except the first Casimir operator that are linear with respect to momentum operators.

The Lorentz invariants  $N^{(1)}, N^{(2)}$  allow to write the equations of Dirac and Maxwell in a uniform form for the states of class  $2j=1, 2$  and to generalize these equations for any  $j$ .

The quantization of the electric, magnetic charge can be regarded as the quantization of the analogue of the spin  $J^{(1)}, J^{(2)}$ , (18), namely.

Generalized Dirac equation for spin 1/2 in the form  $N^{(2)}$ , (14) in the matrix representation is identical to the Dirac equation for electron, positron and has a solution for a particle at rest, corresponding to a state with a mirror antisymmetry and has the projection  $J^{(1)}\Psi = -\Psi/2$  for electron,  $J^{(1)}\Psi = \Psi/2$  for positron. Scalar, Lorentz invariant has the form:

$$Cg_0C^T = \langle \Psi | J^{(1)} | \Psi \rangle = \langle \Psi' | J^{(1)} | \Psi' \rangle.$$

Generalized Dirac equation for spin 1/2 in the form  $N^{(1)}$ , (Equation 15) in the matrix representation is identical to the Dirac equation with matrices  $g, g_0$  with corresponding to Clifford algebra has a solution for a particle at rest, corresponding to a state with a mirror symmetry, and has the projections  $J^{(2)}\Psi = \pm\Psi/2$ , which was named as unknown particle. Pseudo scalar Lorentz invariant, (Jante and Schroers, 2016) has the form:

$$Cg_0g_4C^T = \langle \Psi | J^{(2)} | \Psi \rangle = \langle \Psi' | J^{(2)} | \Psi' \rangle.$$

Generalized Weyl equation for spin 1/2 in the form  $N^{(+)}$ , (Jante and Schroers, 2016) is identical in the matrix representation to the Weyl equation for neutrino, anti-neutrino and has a solution  $\Psi$ , corresponding to a state with the projections  $J^{(3)}\Psi = \pm\Psi/2$ . Since  $\Psi = \psi_k$ , (2) is also the eigenfunctions of the  $Q^{(3)}_3$  and therefore  $\Psi$  does not change shape when the Lorentz transformation. This situation corresponds to a particle moving with the speed of light along  $x_3$  and which may be either right or left,  $J^{(3)}\Psi^{(-)} = -1/2\Psi^{(-)}$ ,  $\Psi^{(-)} = \psi_3$  correspond antineutrinos  $J^{(3)}\Psi^{(+)} = 1/2\Psi^{(+)}$ ,  $\Psi^{(+)} = -\psi_2$ -neutrinos.

Generalized Maxwell equations for class  $2j=2$  in the form  $N^{(1)}$ , (Equation 9) and  $N^{(2)}$ , (Equation 10) in the matrix representations identical respectively the second pair of Maxwell's equations for electrical charge (Equation 11) and the first pair of Maxwell's equations for magnetic charge equal zero (Equation 12). It should be noted that generalized Maxwell's equations (Equations 11 and 12) describe state  $\Psi_{EH}$  without spin.

Principle of superposition of states always performed for states of class  $2j$  in each point and for each orientation  $\phi, \theta$  and  $\gamma$ . The existence of the additional property of principle of superposition of states for the class  $2j=1, 2$  have been revealed in this paper. This property will be named to the property unchangeability (same) functional dependence wave function (analog of

form) of the angular dimensions when states are added. It was found that for spin states  $j=1/2$  there are only two types of independent forms  $\psi_1, \psi_4$  and for class  $2j=2$  there are three types of independent forms  $X^{(p)}_3$  that corresponds different to vector fields.

In accordance with the decisions of generalized Dirac equation, Weyl in nature can only be implemented in three types of point particles for spin  $1/2$ , which are classified according to different types of symmetry and correspond with the three projections of analogue of the spin  $1/2$ ,  $J^{(k)} \Psi = \pm \Psi/2$  respectively for electron at rest, for monopole at rest, for neutrino at flying. A particle and its antiparticle differ a sign of projection  $J^{(k)}$ .

Taking into account that the solutions of the generalized equations, basis states correspond to eigenfunctions of generators of the generalized Lorentz group from  $\phi, \theta$  and  $\gamma$ , it can be concluded next: In nature for spin (vector) states is realized do not just Lorentz group, but generalized an Lorentz group. So some physical systems can be represented more accurately by using a generalized group Lorentz.

The determining role of the generators of the generalized Lorentz group in the formation of the Dirac, Maxwell, and Weyl equations (matrices for the momentum operators (Dirac matrix) and also of irreducible representations of the Lorentz group are shown.

A number of known transformations, such as inversion, Heaviside-Larmor-Raynich, charge conjugation, transition to different representations were equivalently unified and represented using the transformations of the group  $J^{(k)}$  within the framework of transformations of the generalized Lorentz group.

The superconductivity is proposed to be considered as a manifestation of the additional degree of freedom associated with the transformations of the generalized Lorentz group. The generalized Lorentz group in the matrix representation exists regardless of the use or non-use of angular variables. Three bases of the class  $2j=2$ ,  $\psi = X^{(+)}, X^{(-)}, (X^{(3)}, X^{(0)})_0$  correspond to three irreducible representations of the Lorentz group  $(1, 0, 0, 1, 1/2, 1/2)$  and have three Lorentz invariant of  $\Psi$ . The existence of three Lorentz invariants  $\Psi^{(\pm)} = F(\mp) X^{(\pm)}, \Psi_{EH} + \Psi_A/\Lambda$  for the electromagnetic field  $E, H, A, A_0$  leaves the possibility of a transition from one state of  $\Psi$  to another in the framework of the transformations of the generalized Lorentz group and which are composed from linear combination of this three Lorentz invariants. One and the same electromagnetic field corresponding to the Maxwell equations, can correspond to different  $\Psi^{(\pm)} = F(\mp) X^{(\pm)}$  or  $\Psi = \Psi_{EH}$ . The Lorentz invariants  $\Psi_{EH}, \Psi_A$  cannot describe state with spin, chirality, for example of photon, but  $\Psi^{(\pm)}$  can, as  $b^2 \langle \Psi^{(\pm)} | \mathbf{J} | \Psi^{(\pm)} \rangle = \pm 4[\mathbf{E}\mathbf{H}]$  is the direction and value of spin. Given the above, the following mechanism for the transition of a conductor to superconducting state proposed. The low-temperature superconductivity corresponds to a spontaneous transition to spinless state:  $\Psi = \Psi_{EH} + \Psi_A/\Lambda$ .

The high-temperature superconductivity (in iron-based materials) can correspond to a spontaneous transition to left (right) state  $\Psi^{(\pm)}$ , that correspond to chiral superconductors  $J^{(3)} \Psi^{(\pm)} = \pm \Psi^{(\pm)}$ .

The observed difference between left and right chiral superconductivity (Zyga, 2017), when a magnetic field is applied parallel to a superconducting chiral nanotube, electric signals travel in one direction only, can be explained by the existence of a spin of the electromagnetic field proportional to the Poynting vector but differently directed for the left and the right states.

Taking advantage of the fundamental provisions of the theory of groups, whereby the result of operations on one class  $2j=2$  automatically transferred to the result of the same operations on another class  $2j=1$  of the same group, has been offered the following axiom: The transformation  $\gamma' = \gamma + \pi/2$  leads to an exchange of forms  $N^{(1)}$  and  $N^{(2)}$  in generalized Dirac equation and in generalized Maxwell equations, formally leads to the same results, namely: Since generalized Maxwell's equation for a particle of class  $2j=2$  with the electric charge is transformed into generalized Maxwell's equation for particles with a magnetic charge. Matrix representation of this equation in the basis  $X^{(n)}_k, X^{(0)}_0$  coincide with corresponding the equations Maxwell, consequently generalized Dirac equation of class  $2j=1$  for an electron is transformed into generalized Dirac equation for the Dirac monopole. Matrix representation of this equation in the basis  $j=1/2$ , bispinors, (2), also coincide with corresponding the Dirac equations. From the (generalized) equation it follows that is an unknown particle has a mirror symmetry for and coincide with Dirac monopole.

The difference between an electron and the Dirac monopole is difference in types of mirror symmetry, a monopole is a mirror particle and an electron has a mirror antisymmetry. The possibility of the existence of the Dirac monopole is determined by the possibility of the existence of a mirror particle.

The Dirac monopole in a state of rest with spin  $1/2$  has a unique basis with mirror symmetry, that is, it does not change under the inversion, but there are a lot of bases state of spin  $1/2$ , with mirror antisymmetry (the particle passes into the antiparticle). This circumstance, which need to explore and the possible can dramatically reduce the likelihood of the occurrence of such particles (the Dirac monopole), when there is a transition to a unique basic state down to zero.

The subspace of angular dimension plays an important role in the formation of the basic laws of nature. The basic operator  $N^{(\pm)}$  is an analog of the Casimir operator and is written in a symmetric form with respect to the coordinate space and the double orientation space as products of the momentum operators for each spaces.

The existence only of three different (angular, spinor) purely complex representations of the Lorentz group simultaneously in the framework of the generalized

Lorentz group can be considered as a justification for the existence of three generations of leptons (electrons, muons, tau-leptons).

The existence only of three different (angular) purely complex representations of the transpose Lorentz group (as shown in Figure 3) simultaneously in the framework of the generalized Lorentz group can be considered as a justification for the existence of three color charge of quarks.

According to group theory, the result does not depend on the form of the representation. Because, in some cases, compared with the standard matrix approach, the use of operators from angular dimensions has a more obvious physical interpretation, simplicity and generality representation for any  $j$ .

## CONFLICT OF INTERESTS

The authors have not declared any conflict of interests.

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*Full Length Research Paper*

# Correlation of geotechnical parameters with geological formations in a basement complex and its implications on civil structure foundation

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Geotechnical tests were carried out on twenty subsoil samples obtained from ten locations at the depth of 1 and 2 m within Federal University of Technology, Akure, Nigeria. The area is typical of basement complex. The test include; Natural Moisture Content, Grain Size Analyses, Specific Gravity, Atterberg Limits, Compaction, California Bearing Ratio (CBR), and Unconfined Compression Tests. The ten locations where the soil samples were collected were selected across the geological classification of the area. ArcGIS 10.1 software was used to generate maps showing the geotechnical parameters distribution across four geological formations within the area at 1 and 2 m depth. It was observed that the distribution of each geotechnical parameter correlates with the composition of the weathering end-product of the geology. The rocks underlain the area includes; Migimatite Gneiss, Quartzite, Charnockite and Biotite Granite. The poorest geotechnical parameters were obtained within subsoil underlain by Charnockite, hence are most unsuitable soil to host the foundation of civil engineering structures, while the area underlie by weathering end-product of quartzite rock is of good geotechnical parameters and most suitable soil to host the foundation of civil engineering structures. The weathering end-products of Charnockite, Migimatite and Granite rocks give relatively high shear strength than that of quartzite, indicating low cohesive nature of the weathering end-product of quartzite.

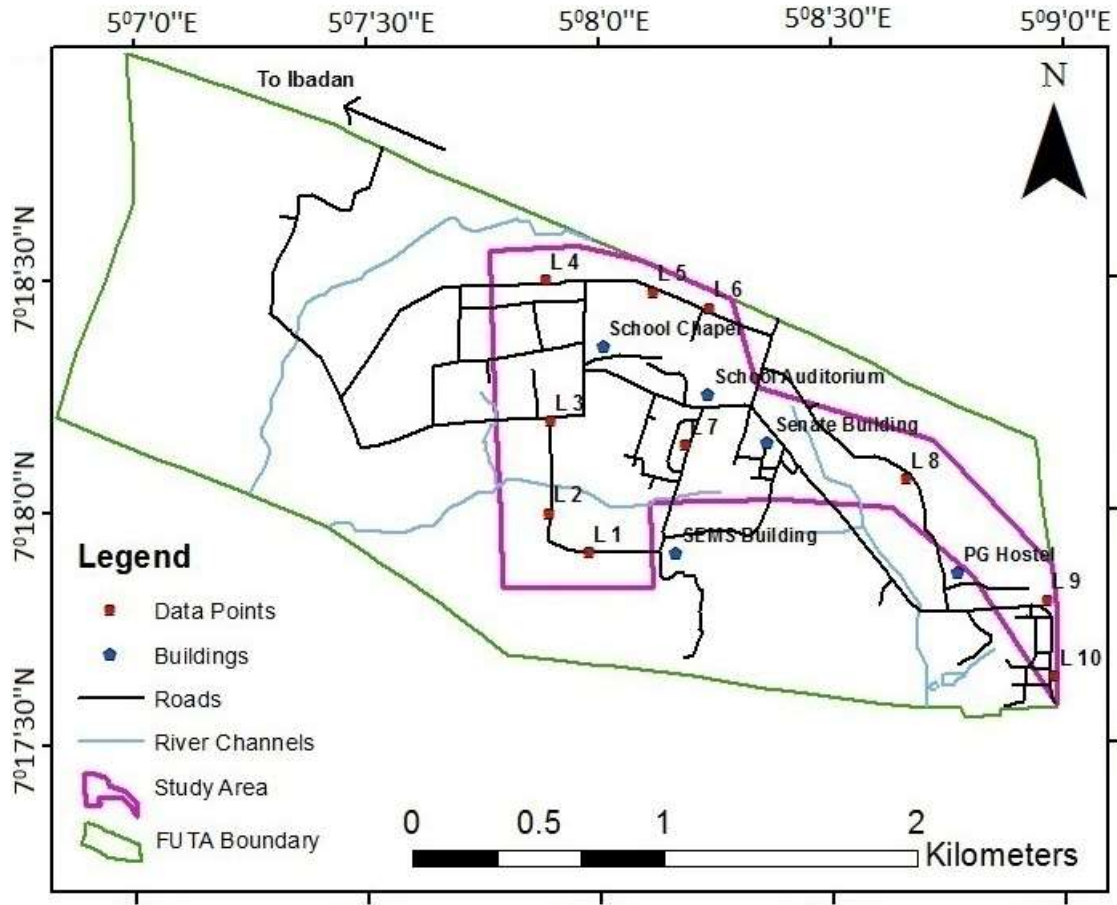
**Key words:** Geological classification, geotechnical parameter, weathering, road base.

## INTRODUCTION

Civil engineering structures are founded on or within the earth. Construction of these structures requires prior investigation of the chosen site in order to derive a good knowledge of the subsoil properties. Lack of the good knowledge of the properties of the subsurface materials leads to the failure of most engineering structures

especially roads and buildings. Therefore, it is of great importance to carry out pre-construction study of a proposed site to ascertain the fitness of the host earth material. The pre-construction investigation may involve direct mechanical boring, pitting and trenching for subsoil sequence delineation, groundwater table mapping, soil

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**Figure 1.** Map of the Federal University of Technology, Akure showing the study area.

sampling, and geotechnical laboratory analysis. It may also involve non-invasive geophysical investigation (Olorunfemi et al., 2010).

For several decades, geotechnical analysis has become increasingly useful in subsurface engineering study to obtain information about the physical and engineering properties of the subsoil which may include the strength, stability and competence of the material that make up the subsoil materials, especially the shallow section which serves as host for foundations of engineering structures (Aina et al., 1996; Adewumi and Olorunfemi, 2005; Idornigie et al., 2006). This information helps the engineers to correctly locate and design the foundation of engineering structures. The information also serves as guide to the choice of design and suitable materials needed for road construction (Akinlabi and Adeyemi, 2014).

The research is aimed at generating maps that will show the distribution of some important geotechnical parameters that are valuable for infrastructure development planning. This will be related to geological distribution within basement complex. The needs to evaluate the subsurface condition as related to geological

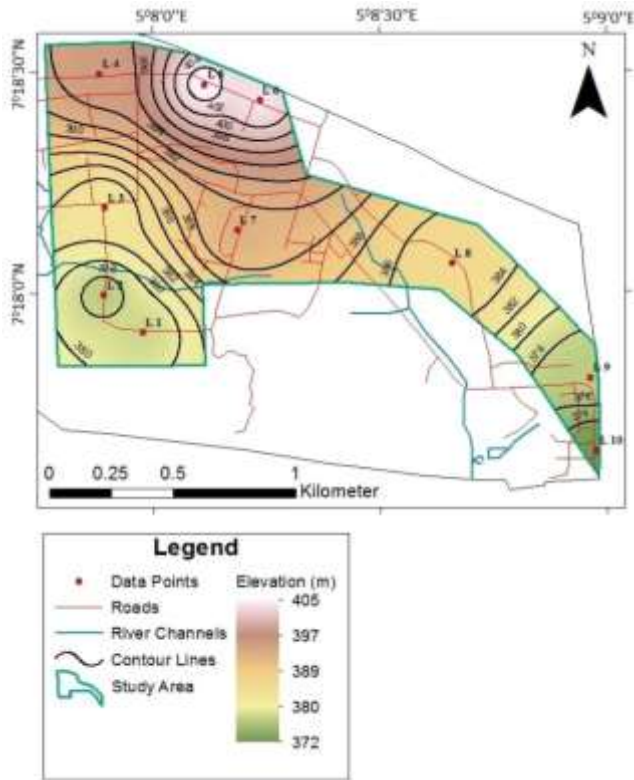
formation for appropriate location of civil structures, proper designing of the foundation of civil structures has necessitated the present research. The study will reveal the distribution of geotechnical parameters across the various geological classifications.

### Description of the study area

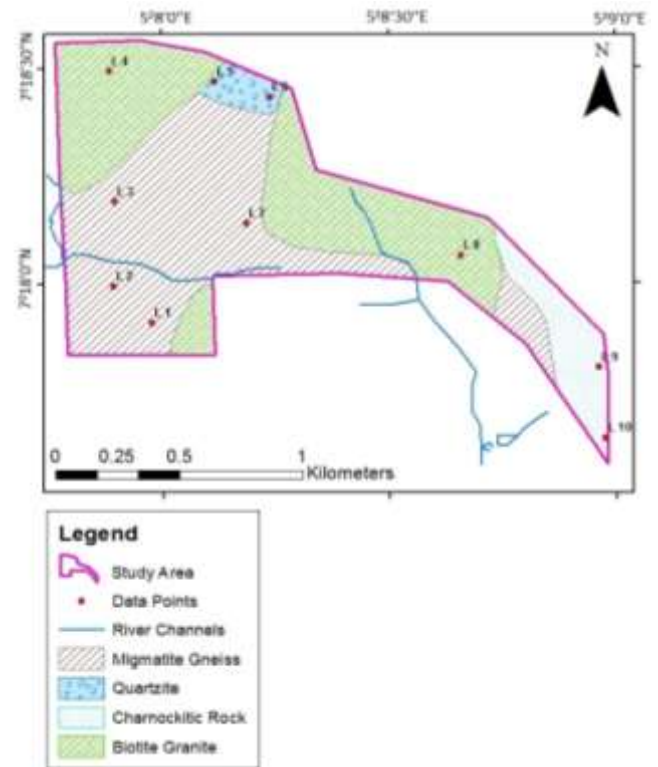
The study area is a part of the Federal University of Technology, Akure Nigeria. The University is situated on the northwestern flank of Akure and occupies an area of about 5 km<sup>2</sup> lies between Latitudes 7°17'0"N – 7° 19'0"N and Longitudes 5° 7'0"E - 5° 9'0"E (Figure 1).

The topography indicates a general gentle slope with gradual increase in elevation from the east and south towards the north-western part of the area (Figure 2).

It has an elevation ranging between 372 and 405 m above mean sea level. There are some stream channels trending approximately east-west and north-south direction. The area is characterized by dry (November to March) and wet (April to October) seasons and mean annual rainfall ranging between 1000 and 1500 mm. The



**Figure 2.** Topographic map of the study area.



**Figure 3.** Geological map of the study area showing the sample points.

Source: Modified after Kareem (1995).

annual mean temperature ranges from 21.9 to 30.4°C. Humidity is relatively high during the wet season and low during the dry season with values ranging annually from 39.1 to 98.2% (Akinbode et al., 2008). The vegetation is of tropical rain forest which is characterized by thick forest.

The area is underlain by rocks of the Precambrian Basement Complex of Southwestern Nigeria (Rahaman, 1989). The dominant rock types are Granite, Charnockite, Quartzite and Migmatite-gneiss (Figure 3). A quartzite ridge that extends over 100 m is located on the northern part of the area. However, Charnockites occur as discrete bodies mainly in the eastern part. Outcrops of migmatite-gneiss occur around the central and the southwestern part of the area. Granites occur as intrusives or lowlying outcrop within the migmatite-gneiss.

Field observation however shows that the granite rocks constitute extensive rock outcrops in the northwestern and northeastern part of the area. The geology and boundaries of lithological units were inferred in places where they are concealed by superficial residual soil (Kareem, 1995).

## MATERIALS AND METHODS

The research methodology consist of both field and laboratory investigations. The field investigation involves visitation to the study

area with the aim of establishing the various geological classifications and boundaries. Ten sampling points were selected across the area based on the geological classifications. Disturbed soil samples were taken at the depth of 1 and 2 m at each sampling points, resulting to a total of twenty (20) soil samples. These were preserved in polythene bags and transported to the laboratory.

The Natural Moisture Content (NMC) of the subsoil samples was determined in the laboratory within the period of 24 h after collection. This was followed by Unconfined Compression Strength (UCS) test on a small portion of the soil samples from each location. The rest of the soil samples were air dried by spreading them out on trays in a fairly warm room for four days. Large soil particles (clods) in the samples were broken with a wooden mallet. Care was taken not to crush the individual particles. All the methods employed in carrying out the geotechnical test complied with the procedures specified by the British Standard Institution BS 1377 (1975).

The other tests carried out on air dried samples include Grain Size Analysis, Specific Gravity, Consistency (Atterberg) Limit, Compaction Test, and California Bearing Ratio.

The change in weight of wet samples put in a can after oven drying were measured and recorded for moisture content test. Sieve analysis test was conducted on oven dried soil samples using set of sieves with mesh size ranging from 4.75 to 0.075 mm after the soil samples have been washed off using sieve with mesh size 0.425 and 0.063 mm which is believed to have removed the clay and silt content. The specific gravity of the soil samples were also determined by obtaining the ratio between the weight of each soil samples and the weight of equivalent volume of water. A Cassagrande device, grooving tool and a spatula were used in the determination of the plastic and liquid limits of the moist soil

**Table 1.** Summary of the results of the subsoil geotechnical test.

Sample locations	Rock Type	Moisture Content (%)	Clay and Silt Content (%)	Specific Gravity	Liquid Limit (%)	Plastic Limit (%)	Plastic Index (%)	Linear Shrinkage (%)	OMC (%)	MDD (kg/m <sup>3</sup> )	CBR (%)	UCSS (Kpa)
<b>Depth of 1 m</b>												
1	Migmatite Gneiss	14.8	34.8	2.639	46.2	36.7	9.5	6.4	13.2	1850	27	78.9
2	Migmatite Gneiss	21.1	35.3	2.694	50	42.9	7.1	9.3	11.86	1788	20	164.9
3	Migmatite Gneiss	24.2	55.6	2.6	54	43.7	10.4	11.4	19.6	1625	12	69.3
4	Biotite Gneiss	15.7	29.2	2.601	36.5	22.5	14	7.1	10.6	1887	45	40.4
5	Quartzite	9.2	24.1	2.802	35	29.2	5.8	4.3	8.3	2142	48	40.6
6	Quartzite	10.1	27.6	2.761	30.6	20.5	10.1	5	11	1978	33	46.5
7	Migmatite Gneiss	17.7	37.8	2.55	24.4	16.2	8.2	5	8.4	2055	41	49.5
8	Biotite Gneiss	19.2	38.4	2.613	42.4	29.9	12.5	7.1	13.6	1978	28	63.1
9	Charnokite	29.2	45.8	2.578	51	31.2	19.8	9.3	20.04	1578	10	112.1
10	Charnokite	21.1	41.28	2.687	42.7	28.8	13.9	9.3	13.2	1878	15	145.7
<b>Depth of 2 m</b>												
1	Migmatite Gneiss	16.7	41.4	2.622	45	34.9	10.2	6.4	13.6	1880	24	73.7
2	Migmatite Gneiss	24.2	48.5	2.676	52	31	21.1	5.7	19.6	1700	15	51.8
3	Migmatite Gneiss	27.3	58.36	2.614	55.5	46.7	8.8	10.7	22.4	1600	13	80.3
4	Biotite Gneiss	22.4	34.2	2.498	44.8	36.7	8.1	5.7	22.02	1639	39	57.1
5	Quartzite	8.3	21.2	2.83	33.1	28.2	4.9	3.6	8.2	2255	54	46.2
6	Quartzite	13.5	38.4	2.601	35.5	23.2	12.3	6.4	14.5	1820	23	46.2
7	Migmatite Gneiss	18.2	29.8	2.631	32	18.7	13.3	7.1	8.6	2070	27	34.6
8	Biotite Gneiss	17.2	26	2.719	38.6	30.3	8.3	5.7	11.4	2052	32	68.5
9	Charnokite	28.2	47.5	2.604	56	34.5	21.5	8.6	22.08	1608	9	106.8
10	Charnokite	20.3	40.88	2.619	45.3	31.7	13.6	7.9	16.4	1804	11	102.7

OMC: Optimum Moisture Content, MDD: Maximum Dry Density, CBR: California Bearing Ratio, UCSS: Unconfined Compression Shear Strength.

samples. The moist samples were also placed in a shrinkage mould and oven dried in order to determine the linear shrinkage limits of the soil samples. Compaction test was done on each of the soil samples using modified protor method that employs 4.5 kg rammer and 5 layers with 25 blows per layer. 6 kg of air dried soil sample was measured and water content of the percentage Optimum Moisture Content (OMC) obtained from the compaction test was added to each soil sample. The wet soil sample was compacted in five layers in the mould by giving each layer 55 uniformly distributed blows of 4.5 kg rammer. From this,

California Bearing Ratio (CBR) test was carried out using the CBR compression machine.

A fairly moist soil sample was compacted in an unconfined compression mould after it has been lubricated with a petroleum jelly. The cylindrical shaped compacted soil of diameter 5.0 cm and height 8.8 cm was used after a period of 24 hours to conduct Unconfined Compression Strength (UCS) test with the aid of the CBR compression machine.

The determined geotechnical parameters of the subsoil samples at the depth of 1 and 2 m for each of the ten

locations was used to generate geotechnical parameter distribution map across the geological classification within the study area at both depths.

## RESULTS AND DISCUSSION

Table 1 show the summary of the geotechnical test results in the study area.



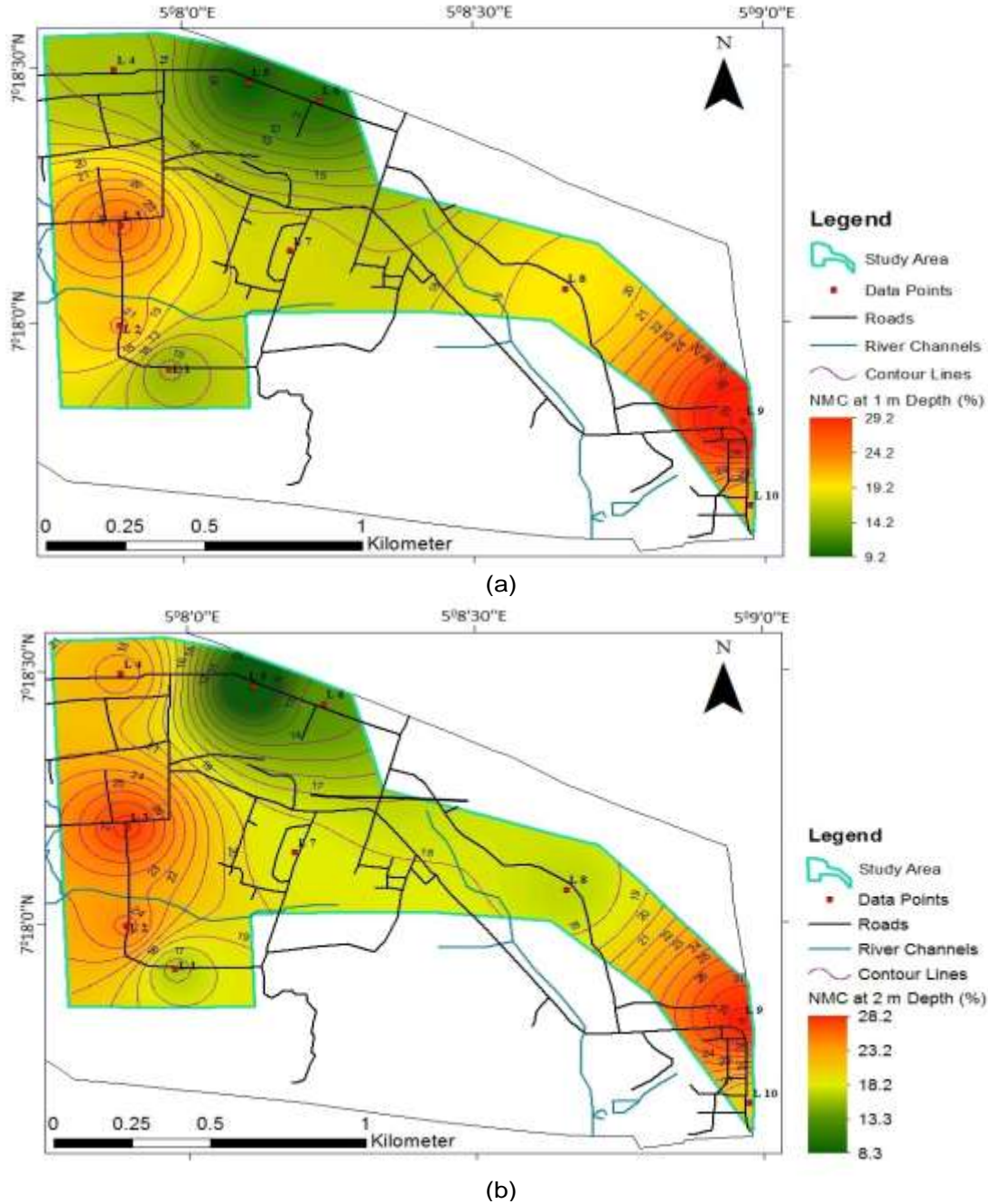


Figure 4. Map of the Natural Moisture Content (NMC) of the subsoil at depth of (a) 1 m and (b) 2 m.

**Natural moisture content (NMC)**

The natural moisture content (NMC) at the depth of 1 and 2 m ranges from 9.2 to 29.2% and 8.3 to 28.2% respectively. The moisture content values are generally high, and may be due to the fact that, the samples were taken during raining season in May, 2017. The highest moisture content (>20%) was observed at south-eastern part of the area (Figure 4), which is underlain by charnockitic rock (Figure 3). The weathering end-product

of charnockite is generally clayey, which is porous but less permeable with tendency of retaining high water content and may have resulted in the high natural moisture content obtained within the south-eastern part of the area. Lowest moisture content values (8.3 to 13.5) were obtained within the area underlain by quartzite (Figure 3). This may be due to the fact that sandy soil which is the weathering end-product of quartzite is porous and permeable, and hence, water drains and percolates easily within it.

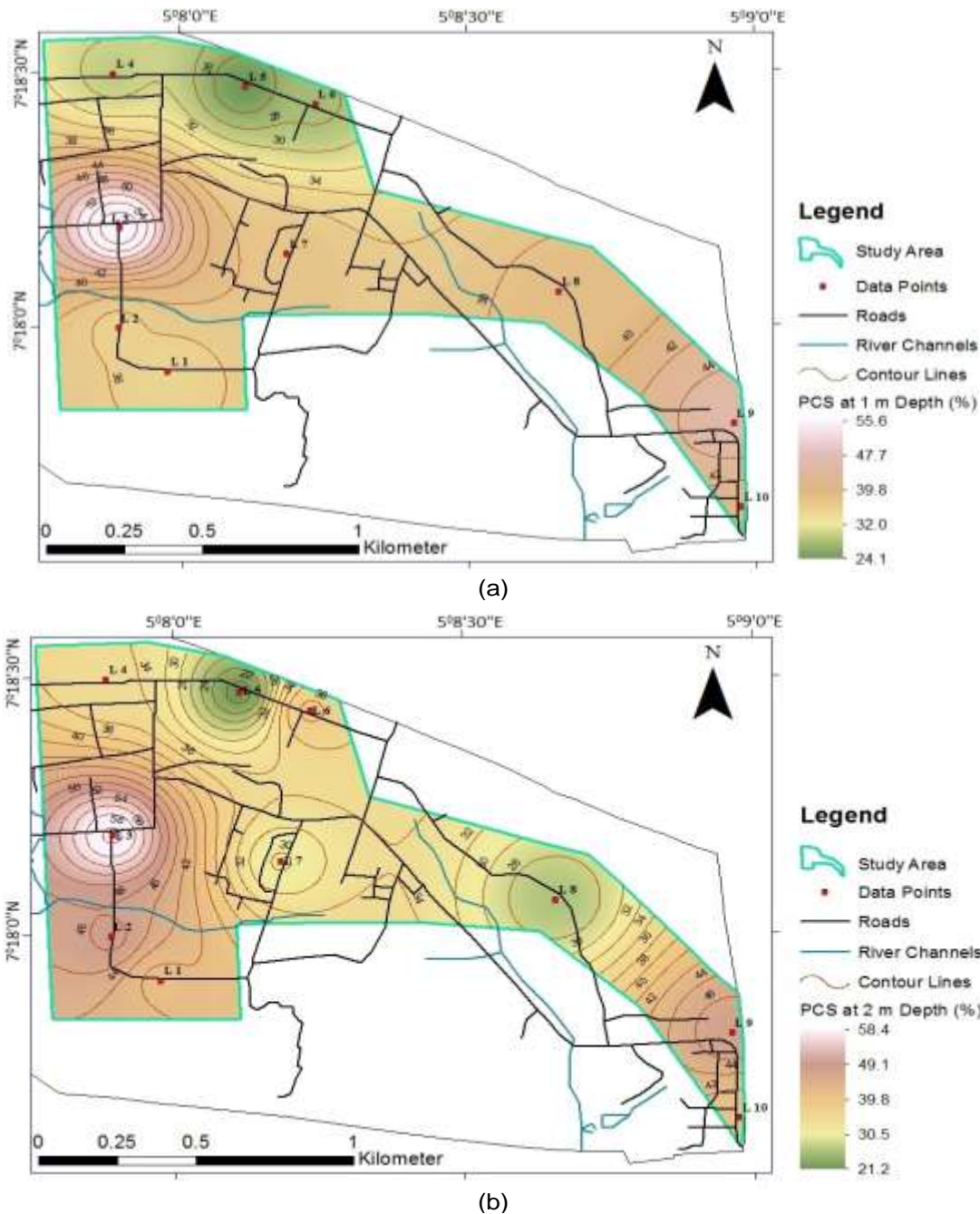


Figure 5. Map of the Percentage of Clay And Silt (PCS) content at Depth of (a) 1 m and (b) 2 m.

**Particle size analysis**

The subsoil at depths 1 and 2 m have percentage passing 0.075 mm sieve ranging from 24.1 to 55.6% and 21.2 to 58.4% respectively (Figure 5). The percentage of soil passing through sieve 0.075 mm is the percentage of clay and silt content contained within the soil. The percentage passing 0.075 mm in the area are higher/slightly higher than the maximum percentage (35%) recommended (Federal Ministry of Works and

Housing (FMWH), 1972) for a good subsoil material for civil eniginering construction purpose. This correlates with the geology of the study area. The lowest value (21.2%) (Table 1) of the percentage passing 0.075 mm sieve was obtained within the area underlain by quartzite (Figure 5), showing that the weathering end-product of quartzite is sandy. Higher values were obtained within the areas underlain by migmatite gneiss and charnockite, which shows that the subsoil within this region is more clayey with the tendency of higher water ratention capacity.

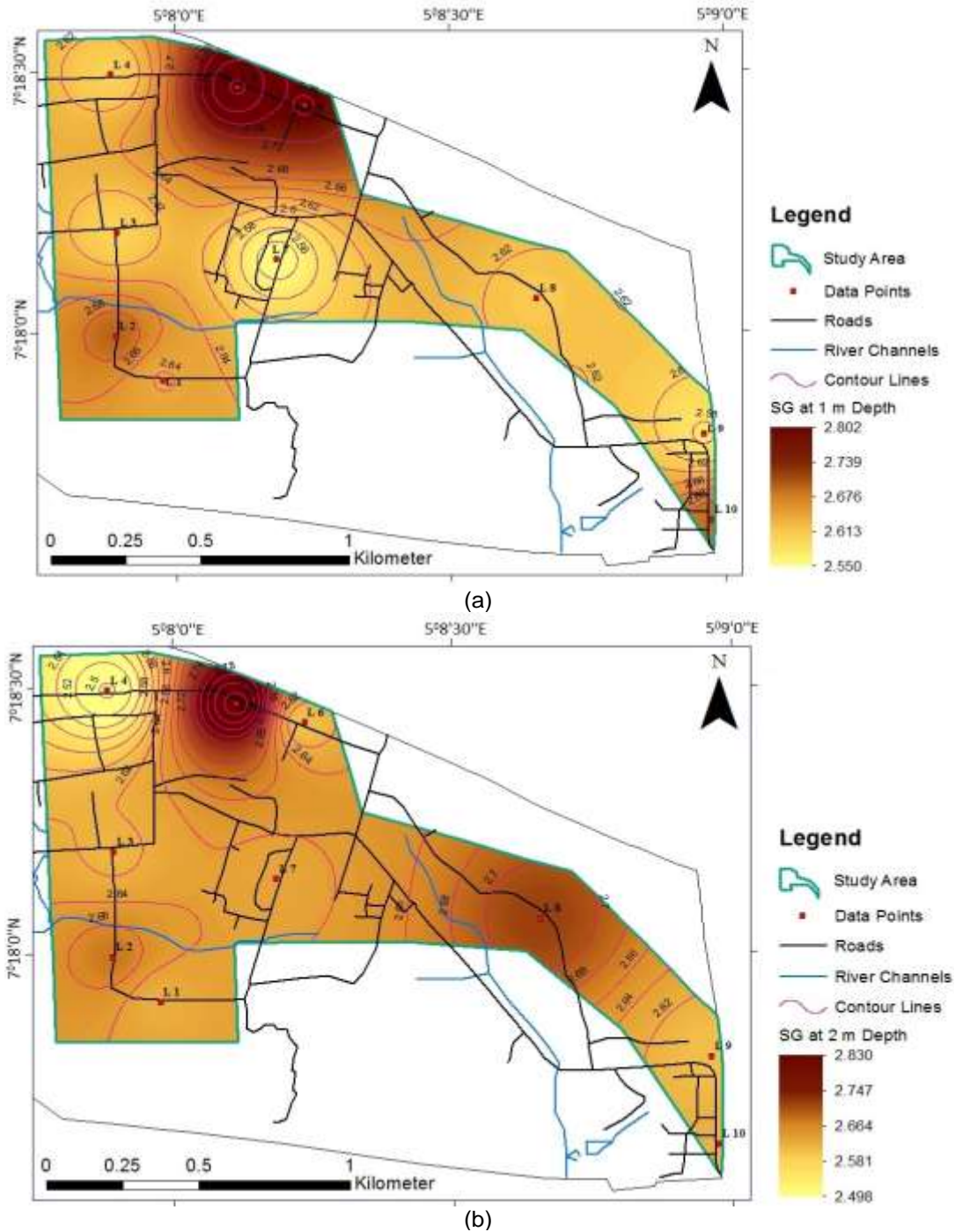


Figure 6. Map of the Specific Gravity (SG) of the subsoil at depth of (a) 1 m and (b) 2 m.

**Specific gravity test**

The specific gravity of soil increases with increasing compaction and decreasing porosity and compressibility. Therefore soils with high specific gravity have good load bearing capacity and strength. The specific gravity values in the study area range from 2.55 to 2.802 and 2.5 to

2.83 at 1 and 2 m respectively (Figure 6). Relatively high specific gravity values were obtained within the areas underlain by quartzite, while areas underlain by other rocks were having relatively low values (Figure 6). This indicates that, the weathering end-product of quartzite is of higher load bearing capacity than the weathering end-product of other existing rocks within the area.

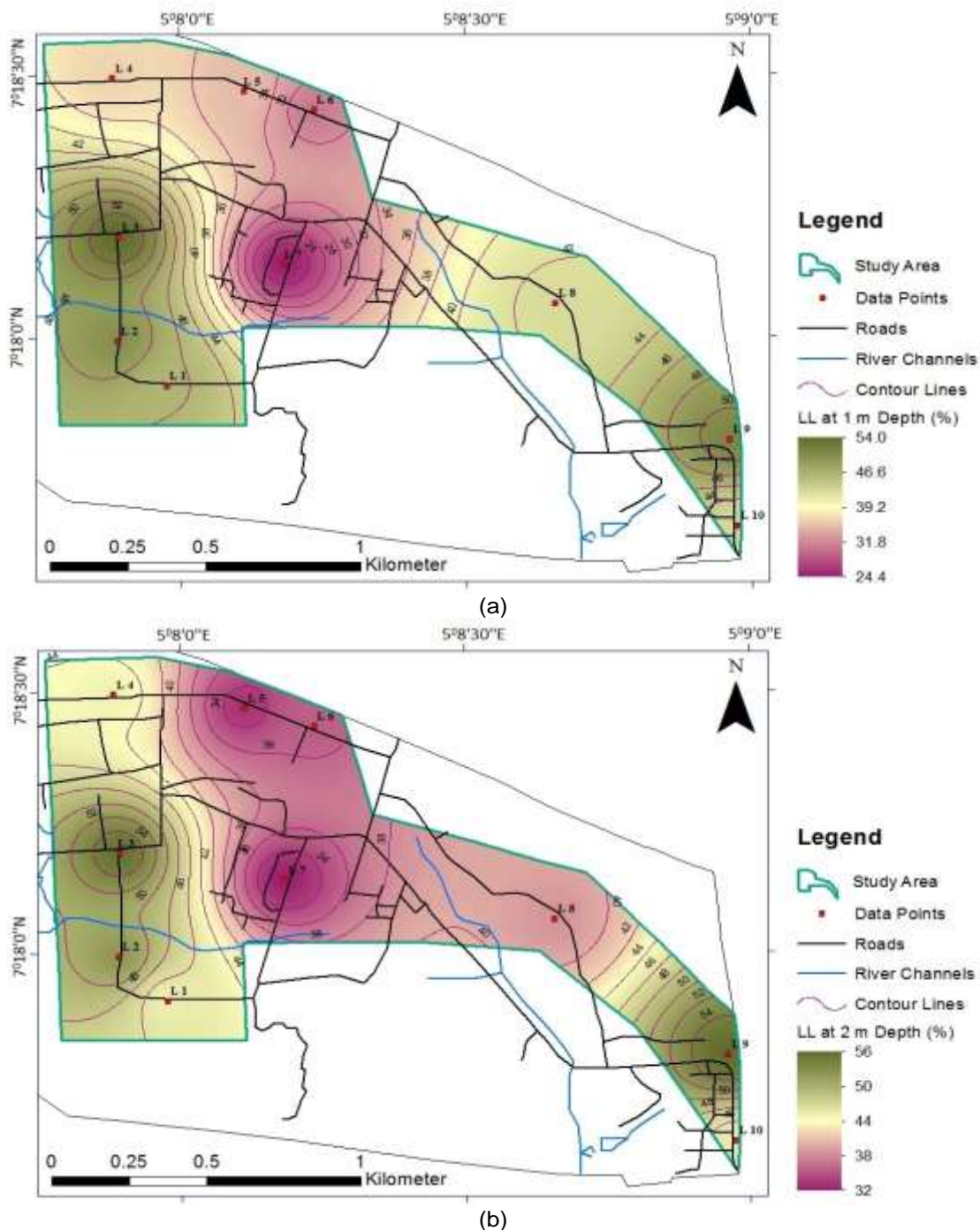


Figure 7. Map of Liquid Limit (LL) of the subsoil at depth of (a) 1 m and (b) 2 m.

### Liquid Limit (LL)

As shown in Figure 7, the Liquid Limit of the subsoil at the depth of 1 and 2 m range from 24.4 to 54% and 32 to 56% respectively. High liquid limit values are indicative of poor engineering and geological properties of subgrade soils (Jegade, 1995). Liquid Limit of 50% maximum (FMWH, 1972) is recommended for sub-grade material

for engineering constructions, and most of the soil samples fall within this value. Therefore the soil can be said to be relatively good to host foundation of any civil engineering structure. However, the subsoil appears to be less competent at the south-eastern and western parts of the area due to the high Liquid Limit values within the regions (Figure 7). The regions are underlain by migmatite and charnockite with higher clayey material as

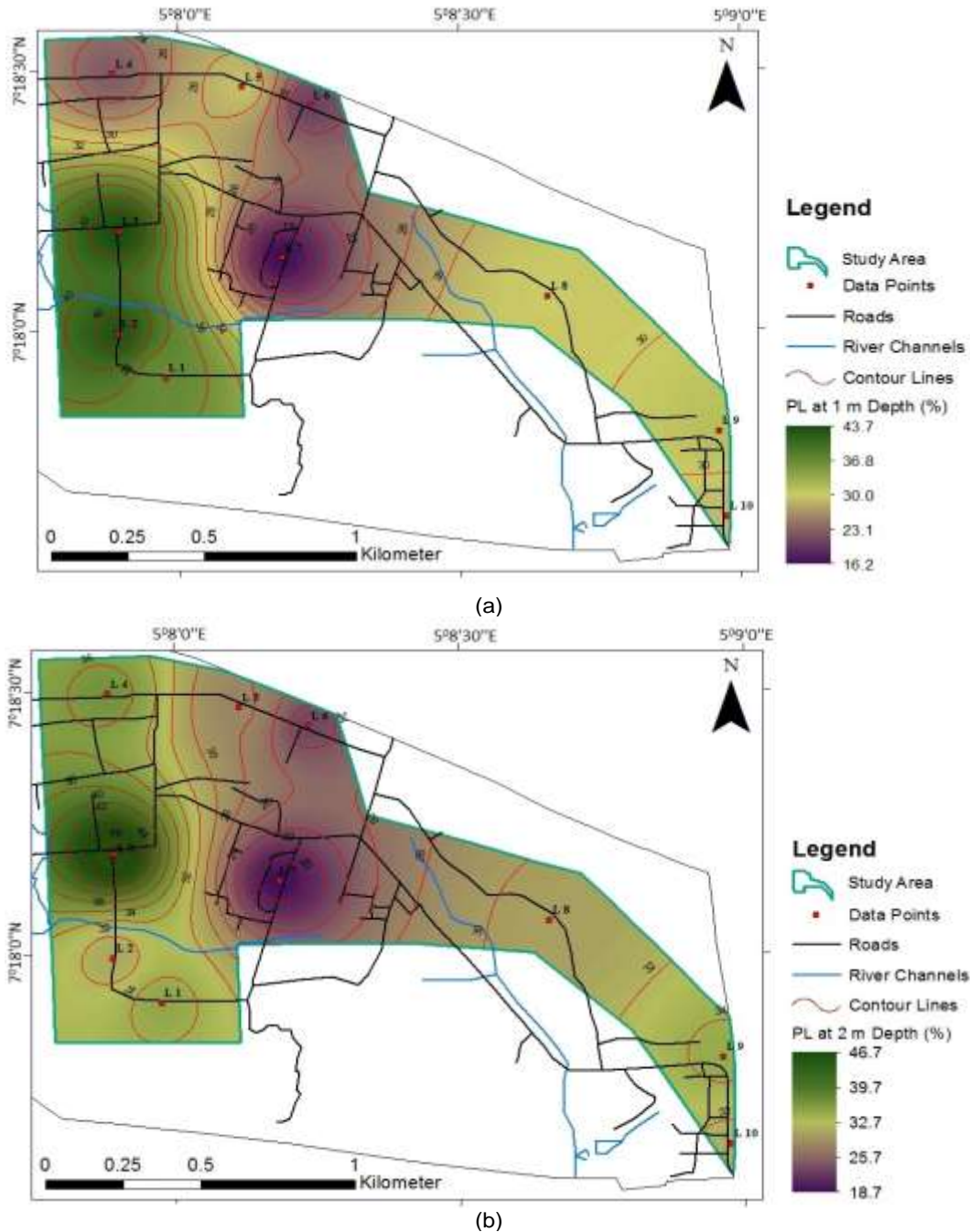


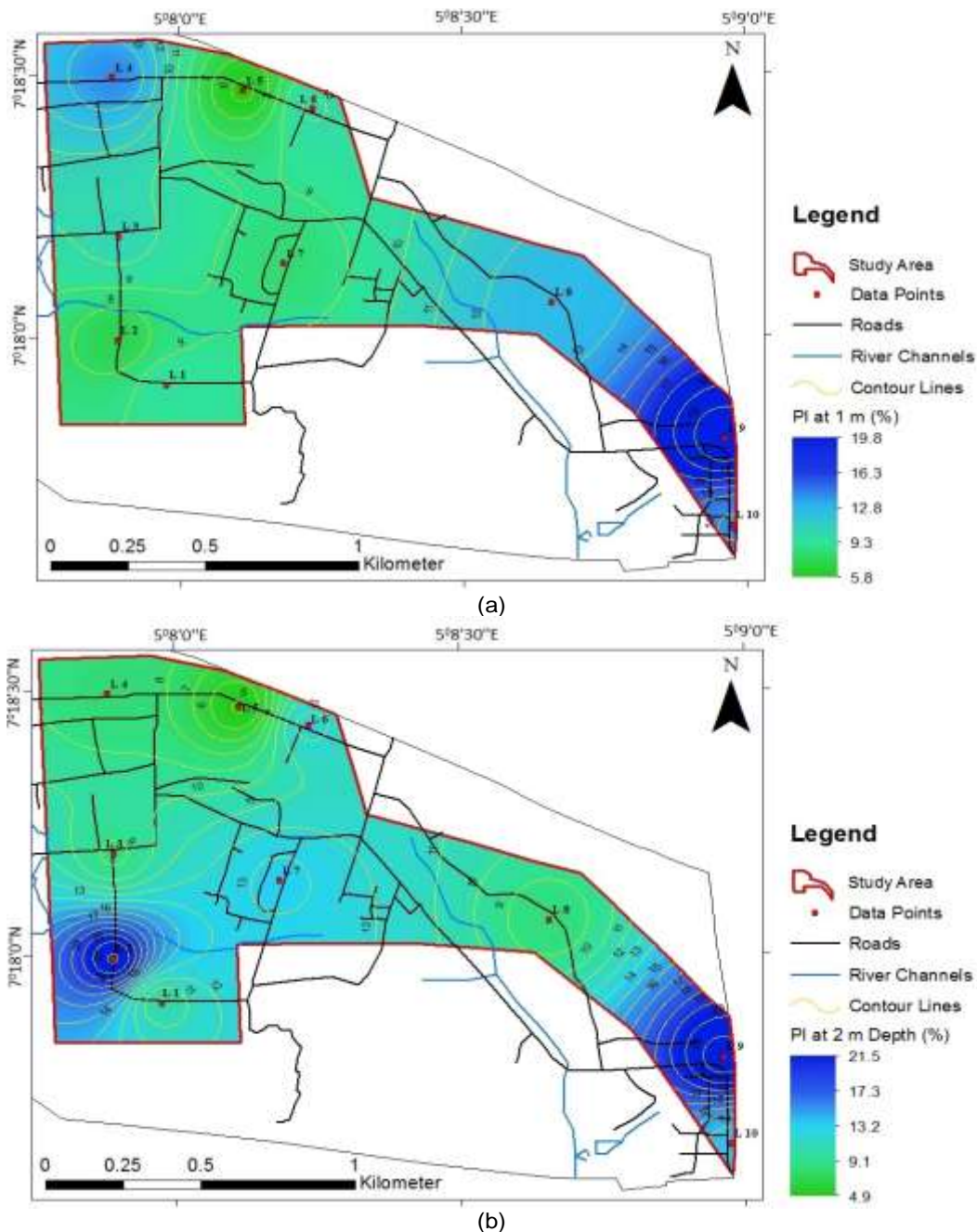
Figure 8. Map of Plastic Limit (PL) of subsoil at depth of (a) 1 m and (b) 2 m.

weathering end-product than quartzite; hence weathering end-product of quartzite rock presents more favorable engineering characteristics than other rock types in the area.

**Plastic Limit (PL)**

Generally, soils having high values of Plastic Limits are

considered as poor foundation materials (Akintorinwa and Adeusi, 2009). The Plastic Limit (PL) of the subsoil at the depth of 1 and 2 m ranges from 16.2 to 43.7% and 18.7 to 46.7% respectively (Figure 8). Plastic Limit of 30% maximum is recommended for sub-grade material for engineering constructions (FMWH, 1972). Most of the tested subsoil falls within this recommended value (Table 1). The high value of Plastic Limit (Figure 8) at southwestern part of the study area must be taken into



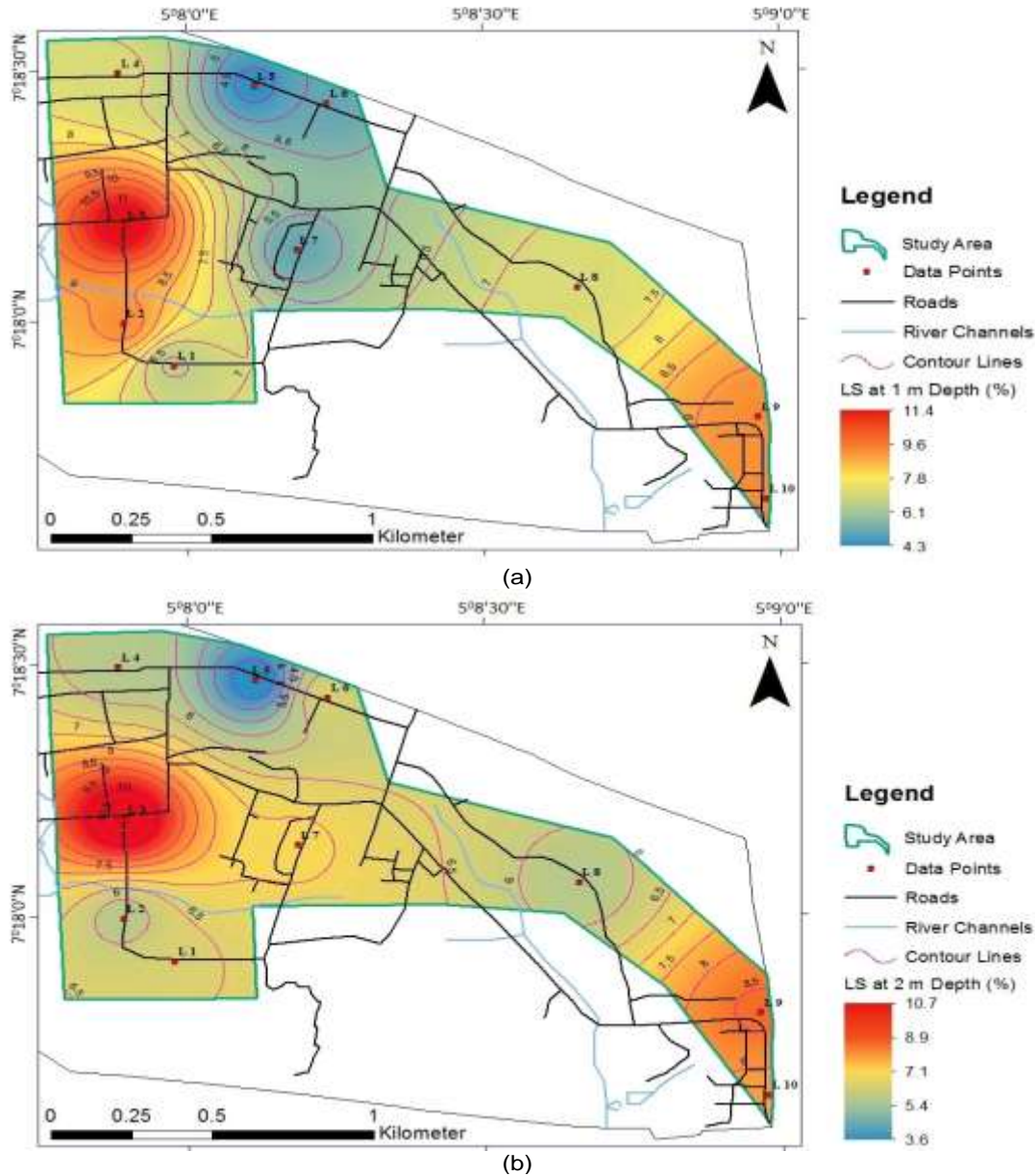
**Figure 9.** Map of Plasticity Index (PI) of subsoil at depth of (a) 1 m and (b) 2 m.

cognizance in erecting any civil structure foundation within the area (Figure 8). The Plastic Limit did present no correlation with any particular geology, but the high values were obtained within the area underlain by migmatite.

**Plasticity Index (PI)**

The plasticity index (PI) of the subsoil at the depth of 1

and 2 m ranges from 5.8 to 19.8% and 4.9 to 21.5% respectively (Figure 9). FMWH (1972) recommended Plasticity Index of 20% maximum for sub-grade material for engineering constructions. The Plasticity Index of the soil samples mostly fall within the recommended range. According to Cassagrande (1972), such soil can be said to be of low to medium compressibility and are therefore suitable for civil engineering construction. Plasticity Index (PI) values slightly higher than 20% were obtained at locations 2 and 9, at the depth of 2 m. Soil samples from



**Figure 10.** Map of Linear Shrinkage (LS) of subsoil at Depth of (a) 1 m and (b) 2 m.

these two locations are of relatively higher compressibility and falls within Charnockite and migmatite lithological units. The lowest value was obtained on subsoil underlain by quartzite rock.

### Linear Shrinkage (LS)

The knowledge of the Linear Shrinkage of soil is very essential in certain geographical areas where soil undergo large volume change when going through wet and dry season's cycle. Generally, the lower the Linear Shrinkage of soil the lesser the tendency of the soil to

shrink when desiccated. The Linear Shrinkage of all the soil samples tested range from 4.3 to 11.4% and 3.6 to 10.7% at 1 and 2 m respectively (Figure 10). Linear Shrinkage value  $\leq 8\%$  is indicative of a soil that is good for sub grade material for engineering construction (Brink et al., 1992; Madedor, 1983). Most of the soil samples fall within the neighborhood of this recommendation. Migmatite and the Charnockite rocks while the lowest value is within the quartzite rock (Figure 10).

Migmatite and the Charnockite rocks while the lowest value is within the quartzite rock (Figure 10). Migmatite and the Charnockite rocks while the lowest value is within the quartzite rock (Figure 10). The weathering end-

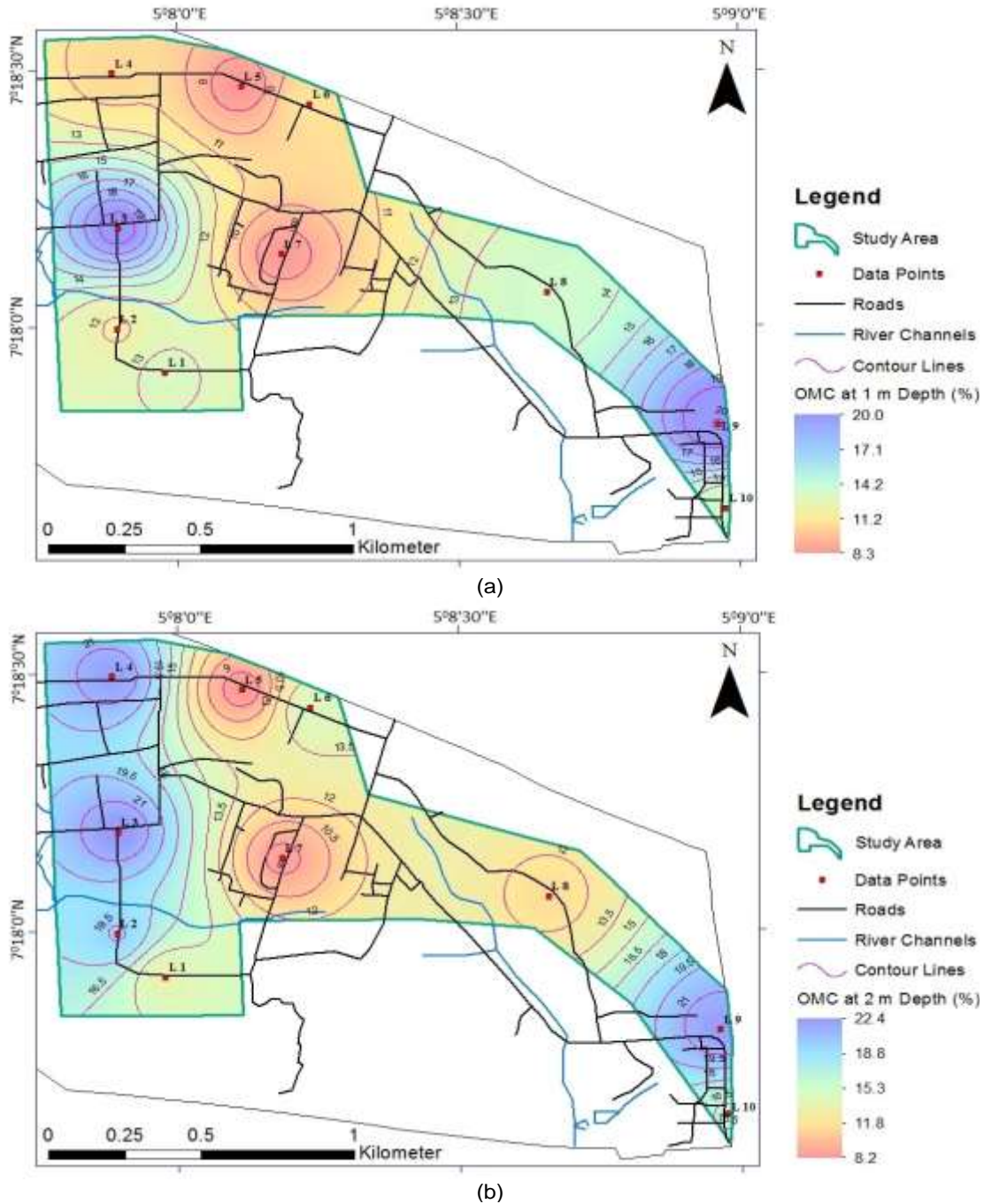


Figure 11. Map of Optimum Moisture Content (OMC) of subsoil at depth of (a) 1 m and (b) 2 m.

product of Migmatite and Charnockite rocks usually contains high percentage of clay than other rock types and they consequently have more tendencies to shrink.

**Compaction characteristics**

The importance of compaction test is to improve the desirable load bearing capacity properties of a soil

(Akintorinwa and Adeusi, 2009). The degree of compaction is sensitive to moisture content. The best subsoil for foundation of engineering structures is that with high Maximum Dry Density (MDD) at low OMC (Jegade, 1999). The Optimum Moisture Content (OMC) values of the soil samples at 1 m depth range from 8.3 to 20.04%, and that of 2 m depth range from 8.2 – 22.08% (Figure 11). It was observed that soil samples within quartzite (Figure 11) have the least OMC, while the high



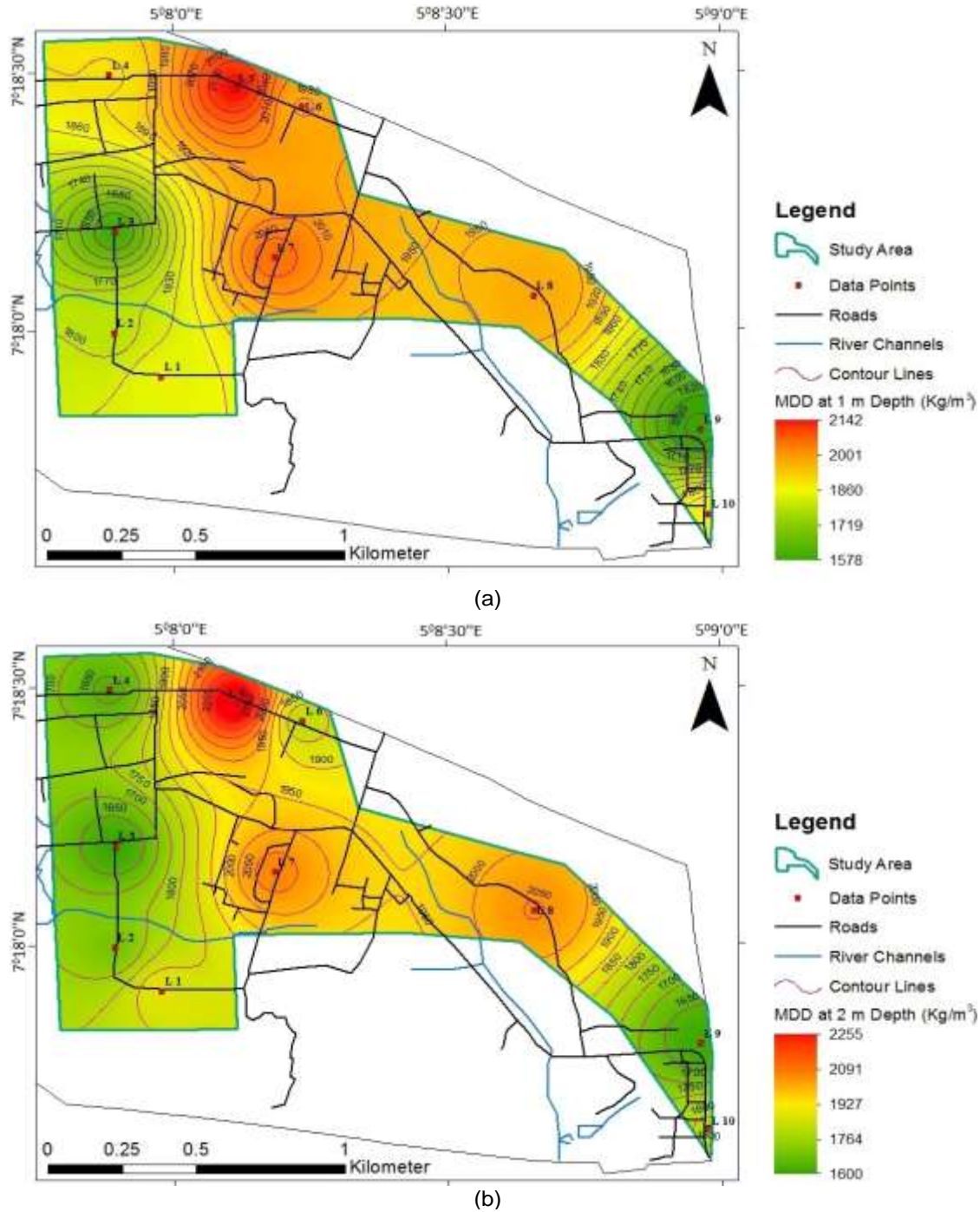


Figure 12. Map of Maximum Dry Density (MDD) of subsoil at depth of (a) 1 m and (b) 2 m.

OMC values were obtained within the area underlain by Charnockite, Granite and Migmatite (Figures 2 and 11).

The MDD is the density of the soil at which any further increase in the moisture content leads to a reduction in the unit weight of the soil. The MDD values ranges from 1578 to 2142 kg/m<sup>3</sup> and 1600 to 2255 kg/m<sup>3</sup> at depths of 1 and 2 m (Figure 12). It was also observed that the subsoil within quartzite with the least OMC (8.2 and

8.6%) have the highest MDD (2055 and 2255 kg/m<sup>3</sup>). The highest OMC (19.6 and 22.4%) have the lowest MDD (1578 and 1625 kg/m<sup>3</sup>) was obtained within Migmatite and Charnokite (Figures 2, 11 and 12). This implies that quartzite rock have better compaction characteristics than other rocks. The weathering end-product of rocks that are clayey may have poor compaction characteristics.

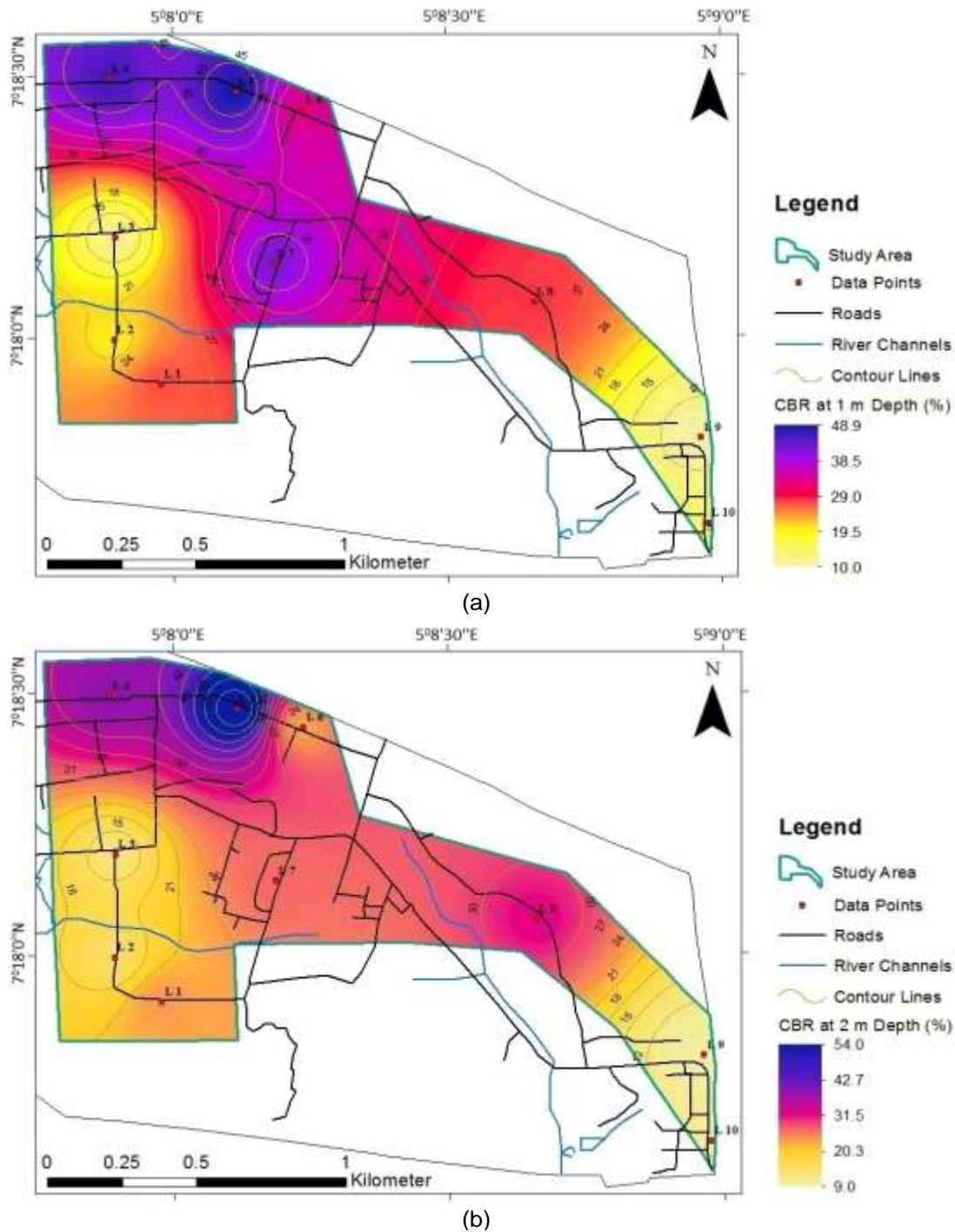


Figure 13. Map of California Bearing Ratio (CBR) of subsoil at depth of (a) 1 m and (b) 2 m.

**California Bearing Ratio (CBR)**

California Bearing Ratio (CBR) is a test designed to assess the strength of soil. The California Bearing Ratio (CBR) of the subsoil at the depth of 1 and 2 m range from 10 to 48% and 9 to 54% respectively (Figure 13). The standard specification of CBR recommended according

to FMWH (1972) is 80% minimum for subgrade materials for road construction in Nigeria.

The CBR test results has shown that none of the soil samples tested has CBR value up to 80% minimum recommended for road construction. This cuts across all the lithological units but high value was obtained within area underlain by quartzite (Figure 13).

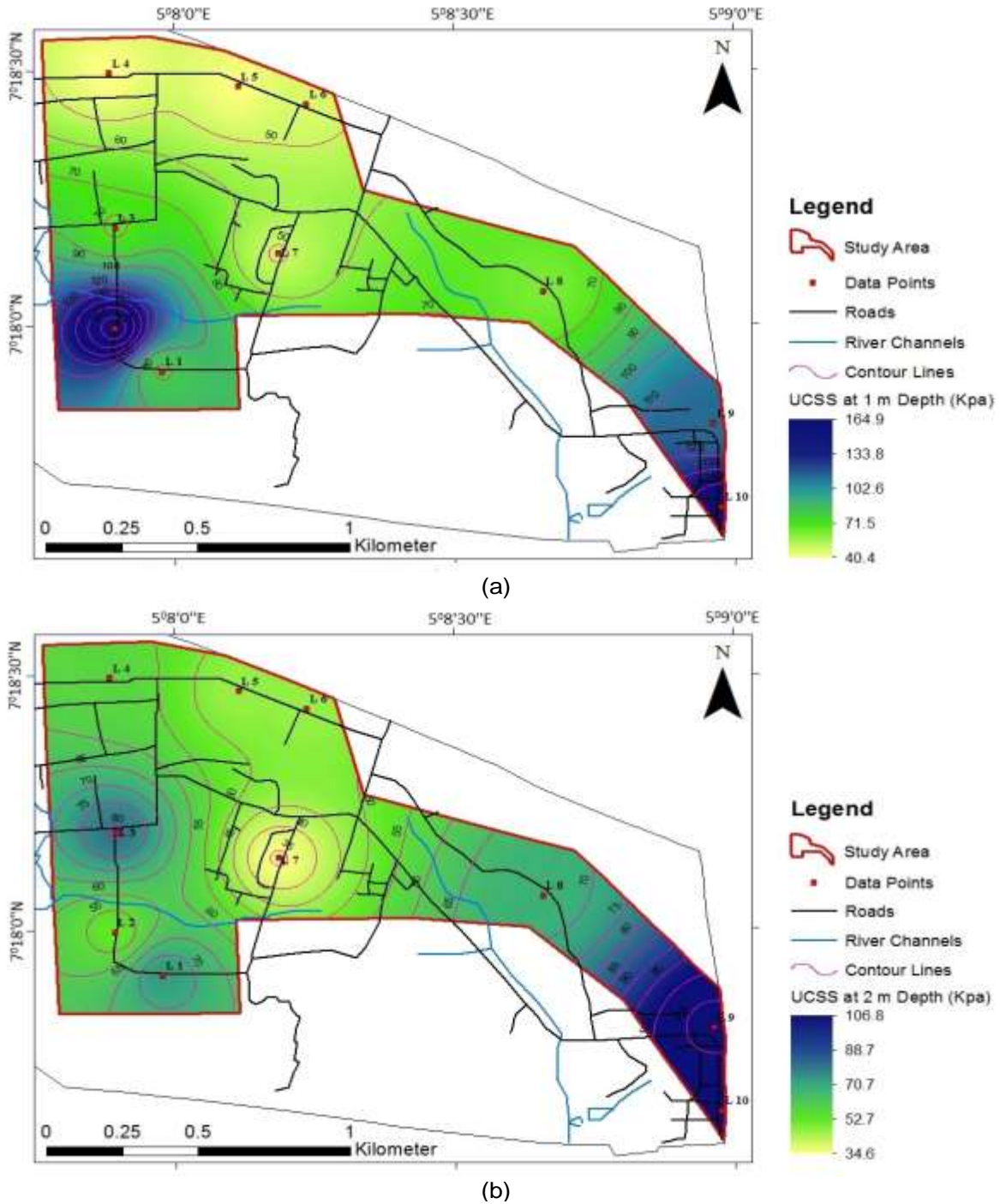


Figure 14. Map of Unconfined Compression Shear Strength (UCSS) of subsoil at depth of (a) 1 m and (b) 2 m.

**Unconfined Compression Shear Strength (UCSS)**

The unconfined compression strength test is highly reliant on the cohesive qualities of the binder of the soil particles resulting from the clay content. The unconfined compressive shear strength ranges from 40.4 to 164.9 Kpa for the soil at the depth of 1 m, while it ranges from

34.6 to 106.8 Kpa for soil at the depth of 2 m (Figure 14). These soils can be classified as medium to stiff subsoil. The south-eastern and south-western parts of the study area where the subsoil have relatively high percentage of clay content have high UCSS values, hence high cohesive quality of binder material; whereas, reverse is the case for other parts of the study area. The lowest

value at the depth of 1 m was obtained within area underlain by quartzite rock (Figure 14a). The weathering end-product of quartzite may not be suitable as binding material for its low cohesive nature.

## Conclusion

The geotechnical tests include; natural moisture content, grain size analyses, specific gravity, Atterberg limits, compaction, California bearing ratio (CBR), and unconfined compression tests was conducted across four geological formations in a typical Basement complex. The rock includes; Migimatite Gneiss, Quartzite, Charnockite and Biotite Granite. The obtained results show that the geotechnical parameters correlate with the weathering end-product of the geology. The poorest geotechnical parameters were obtained within subsoil underlain by Charnockite, hence are most unsuitable soil to host the foundation of civil engineering structures, while the area underlie by weathering end-product of quartzite rock is of good geotechnical parameters and most suitable soil to host the foundation of civil engineering structures. The weathering end-products of Charnockite, Migimatite and Granite rocks give relatively high shear strength than that of quartzite, indicating low cohesive nature of the weathering end-product of quartzite.

## CONFLICT OF INTERESTS

The authors have not declared any conflict of interests.

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